



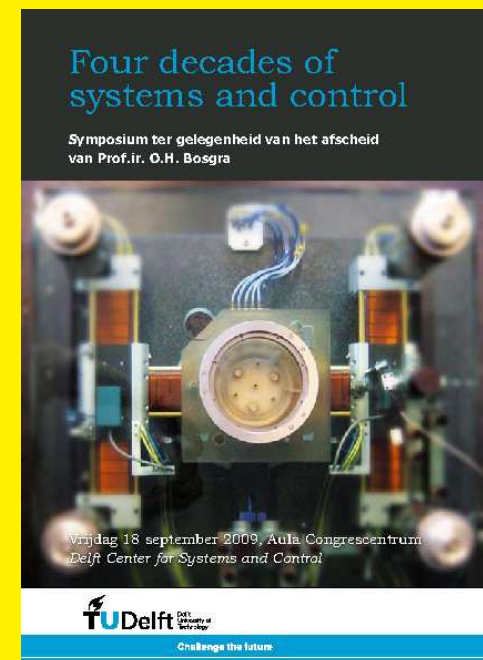
THE RIGHT CONNECTION

JAN C. WILLEMS
K.U. Leuven

Symposium
Four decades of Systems and Control



September 18, 2009





Ter gelegenheid van het afscheidscollege van Okko Bosgra

In honor of Okko Bosgra



on the occasion of his ‘last lecture’.

De juiste connectie



The right connectie

How are systems interconnected?

- ▶ **Is output-to-input assignment a good way of viewing interconnection of physical systems?**

How are systems interconnected?

- ▶ Is **output-to-input assignment** a good way of viewing interconnection of physical systems?
- ▶ Interconnection by **variable sharing.**

How are systems interconnected?

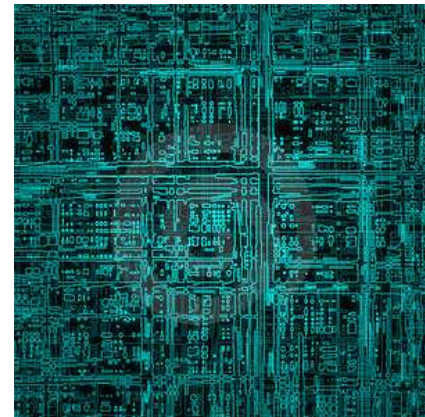
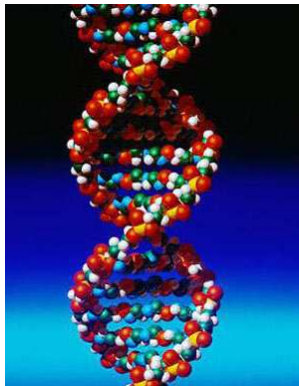
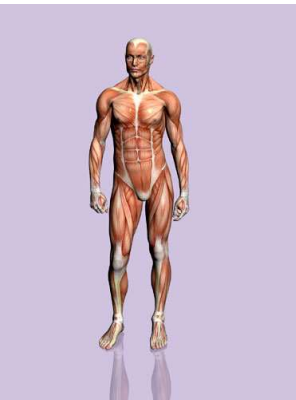
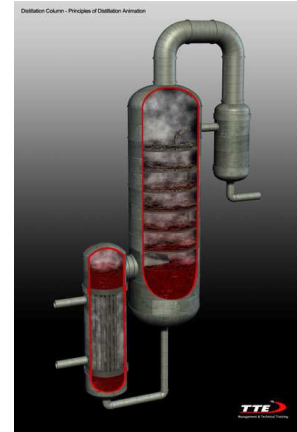
- ▶ Is **output-to-input assignment** a good way of viewing interconnection of physical systems?
- ▶ Interconnection by **variable sharing**.
- ▶ How is energy transferred between systems?
Are **energy transfer and interconnection** related?

SYSTEMS

Systems



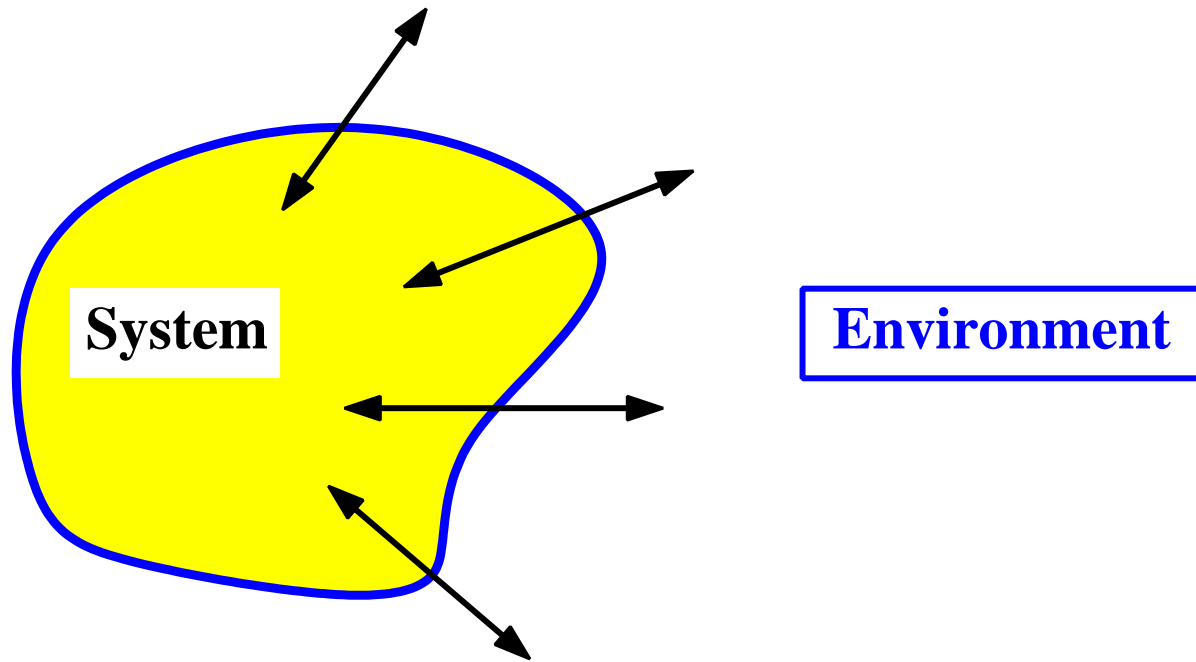
OIL REFINERY (GVG / PD)



Features

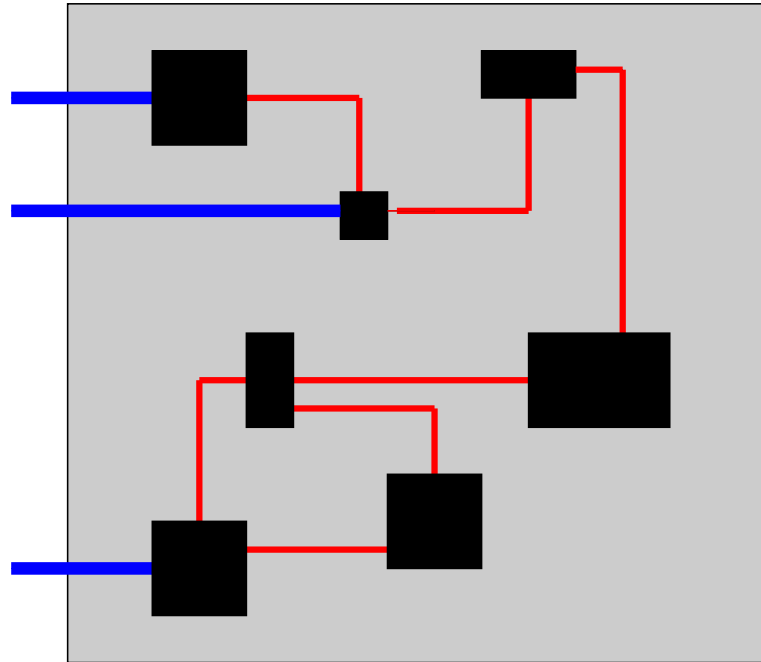
- ▶ **Open**
- ▶ **Interconnected**
- ▶ **Modular**
- ▶ **Dynamic**

Open



Systems interact with their environment.

Interconnected



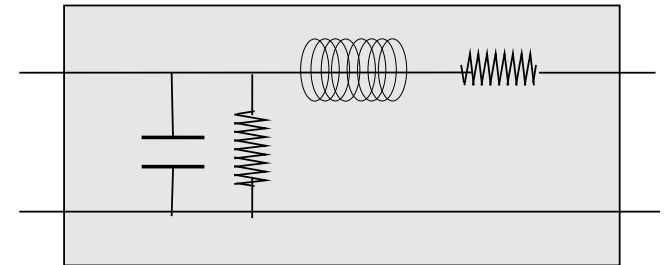
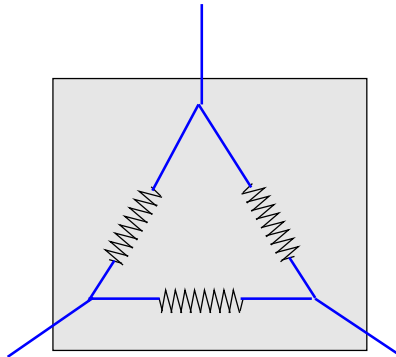
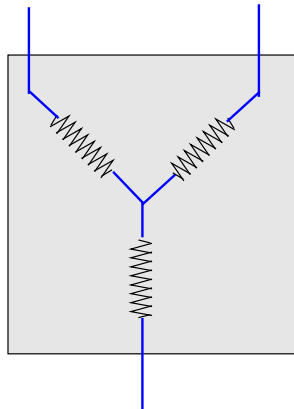
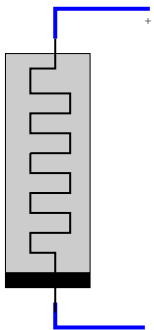
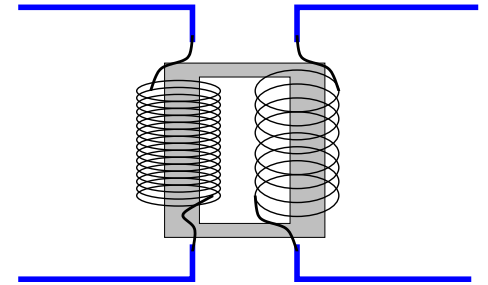
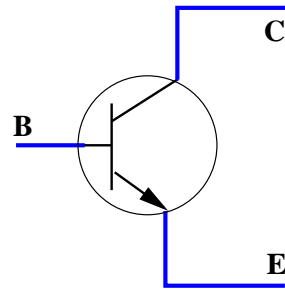
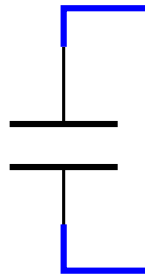
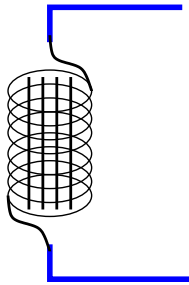
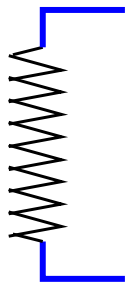
Systems consist of interconnected subsystems.

Modularity

Systems consist of interconnection of standard components.

Modularity

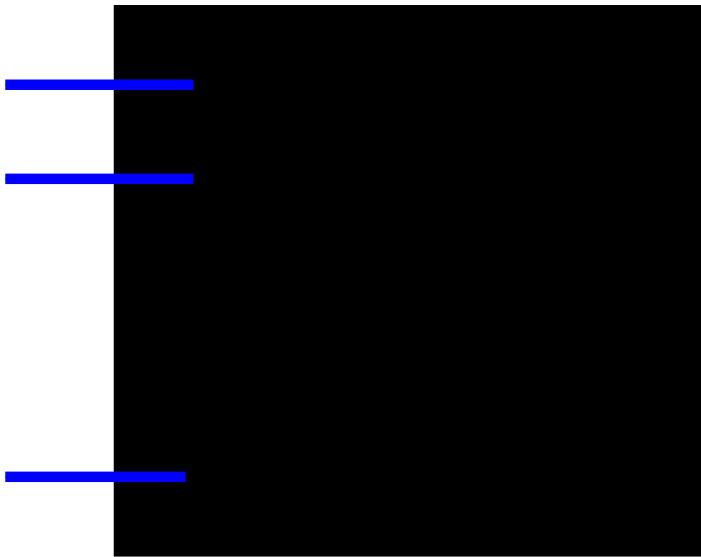
Systems consist of interconnection of standard components.



TEARING, ZOOMING, and LINKING

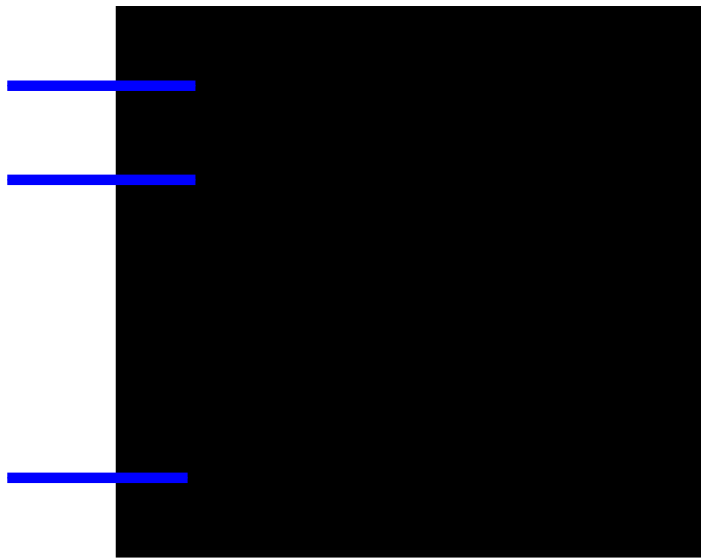
Tearing

∴ Model the behavior of selected variables !!

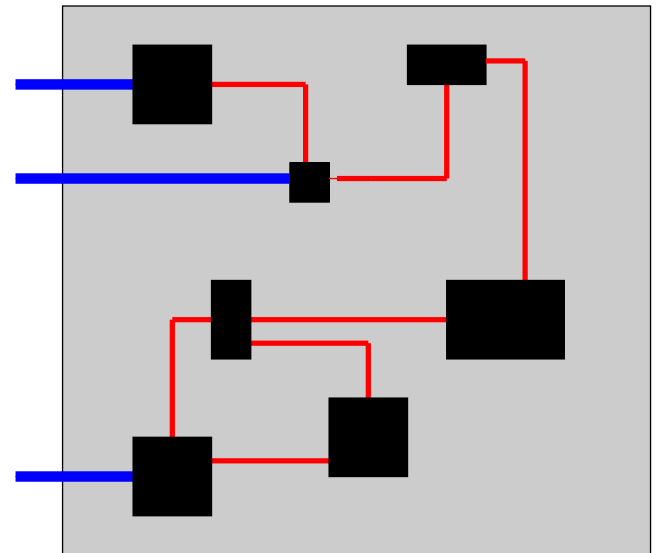


Tearing

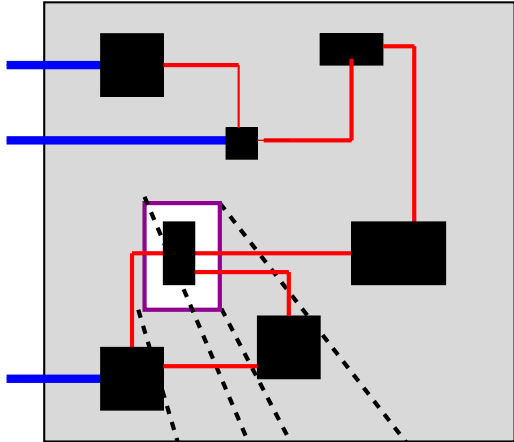
∴ Model the behavior of selected variables !!



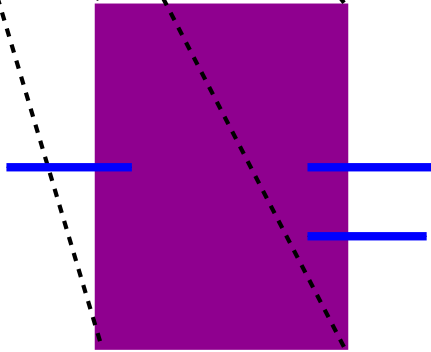
Tear



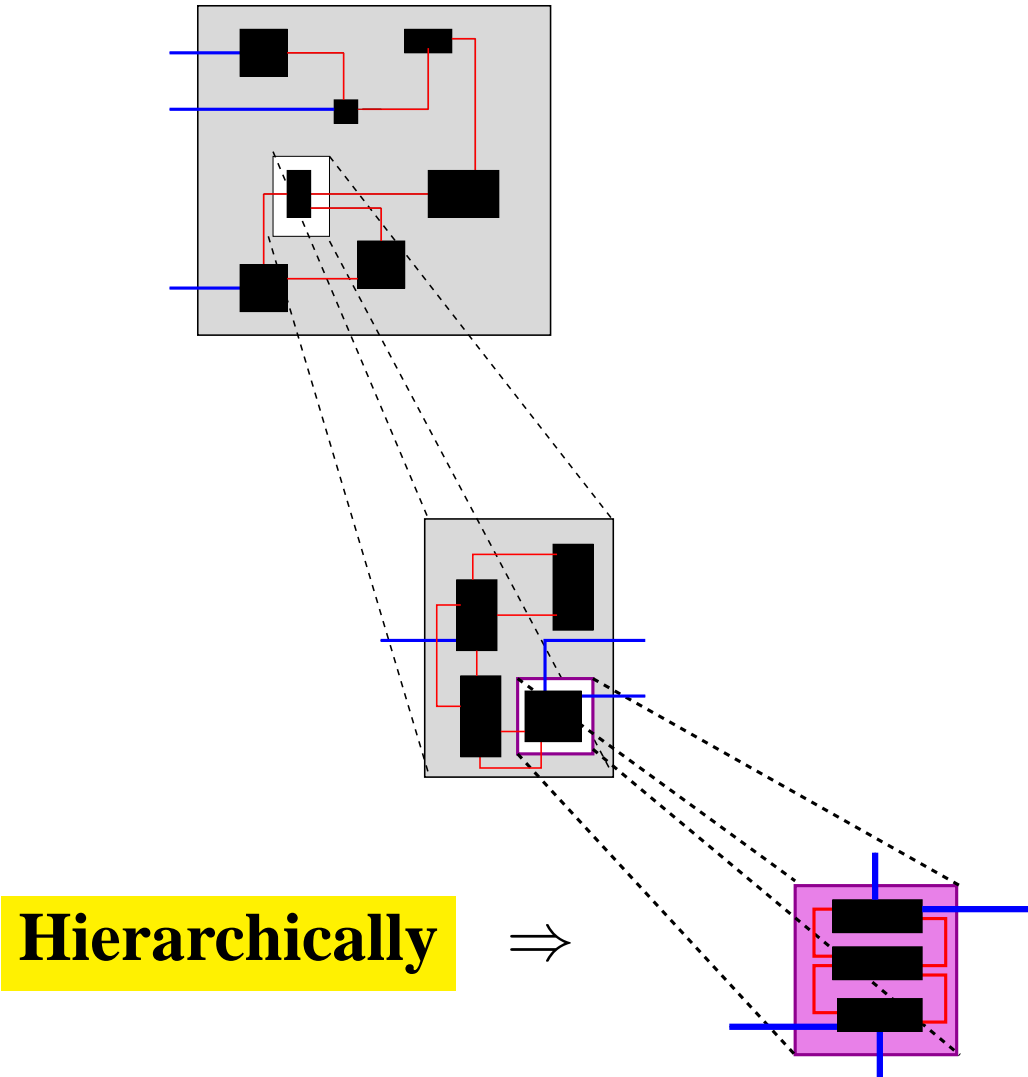
Zooming



Zoom

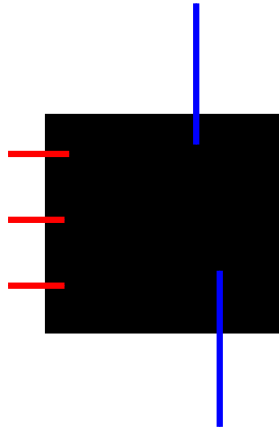
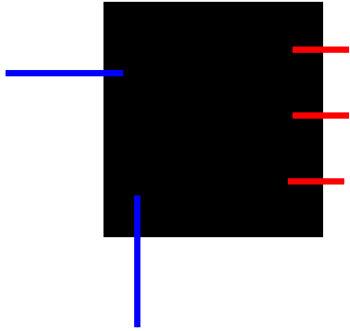


Zooming

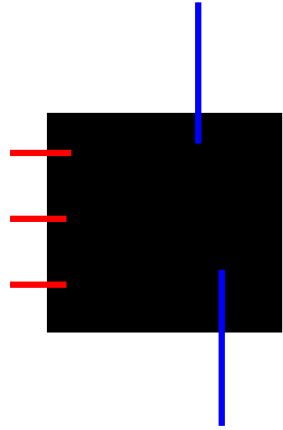
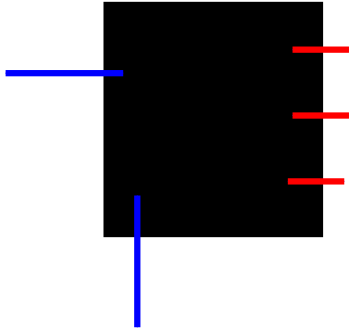


Proceed until subsystems (‘modules’) are obtained whose model is known, from first principles, or stored in a database.

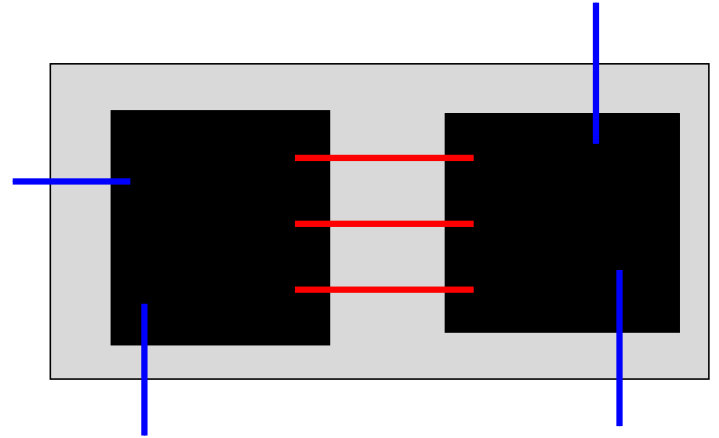
Linking



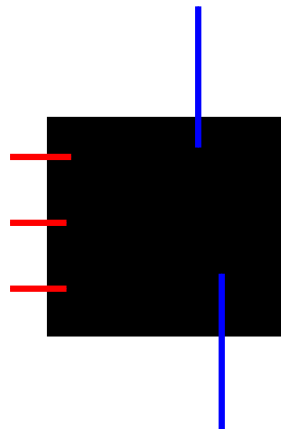
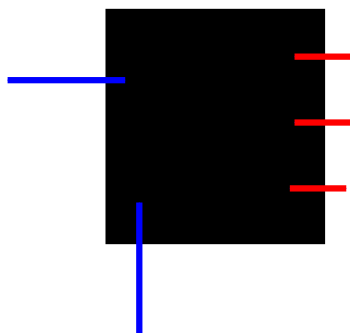
Linking



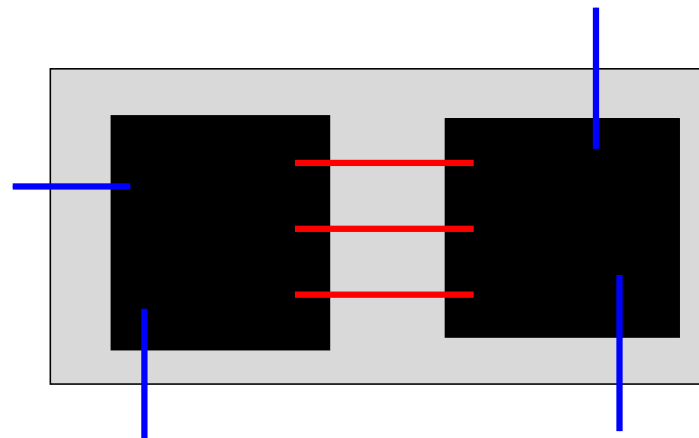
Link



Linking



Link



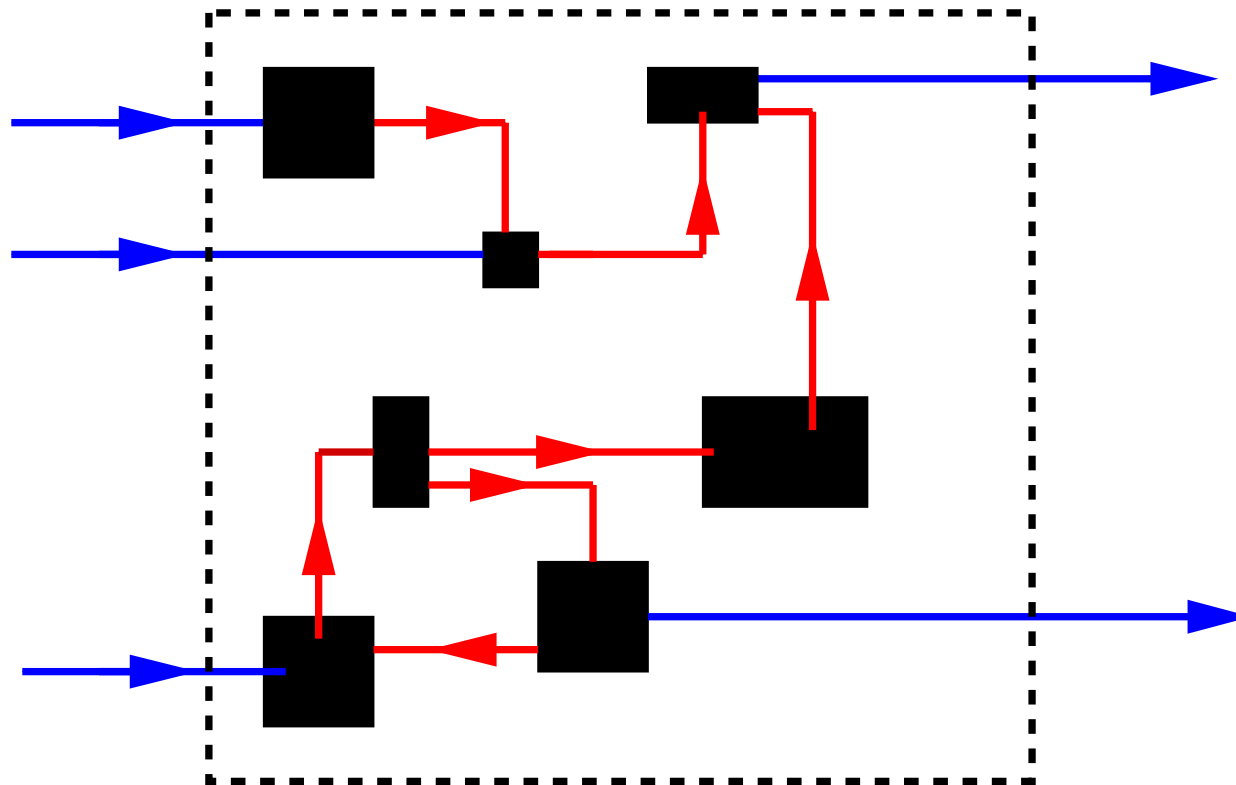
Today's theme: **How should we formalize linking?**

Is there special structure to this linking?

OUTPUT-to-INPUT ASSIGNMENT

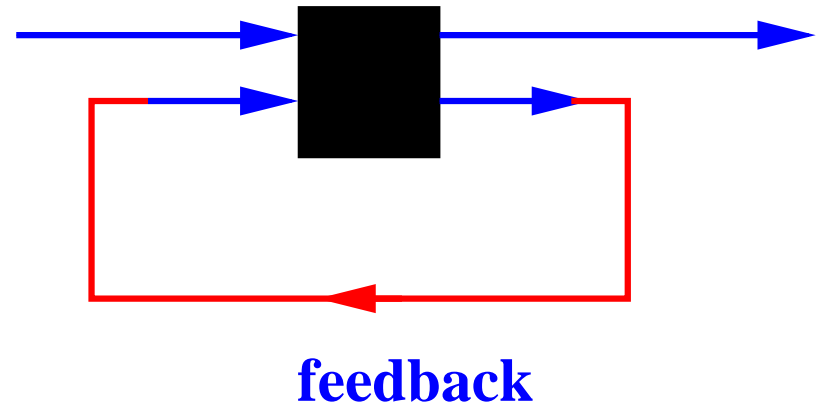
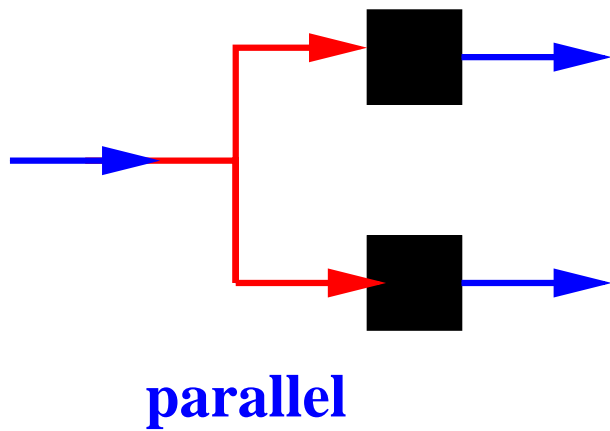
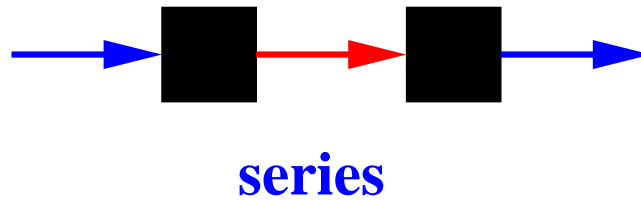
Signal flow graphs

View systems as signal flow graphs:

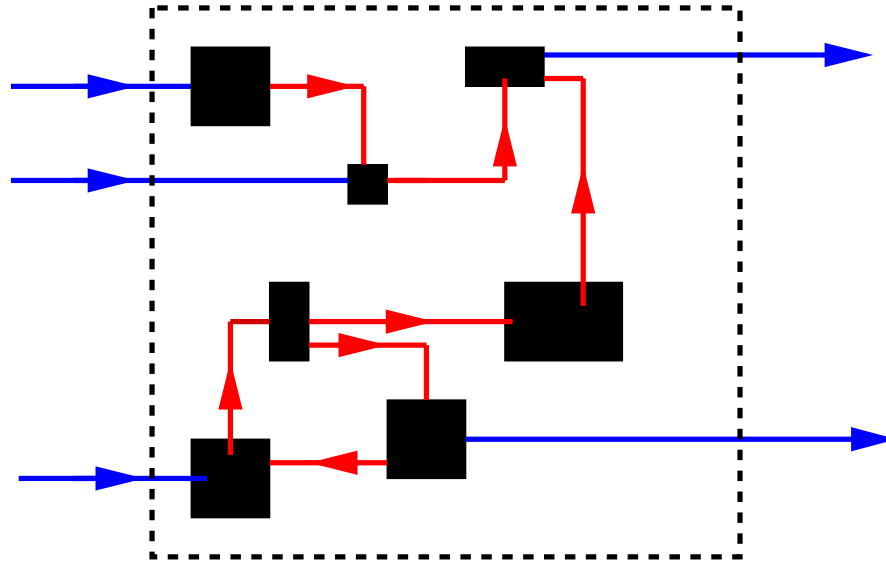


Signal flow graphs

View interconnection as output-to-input assignment:



Signal flow graphs

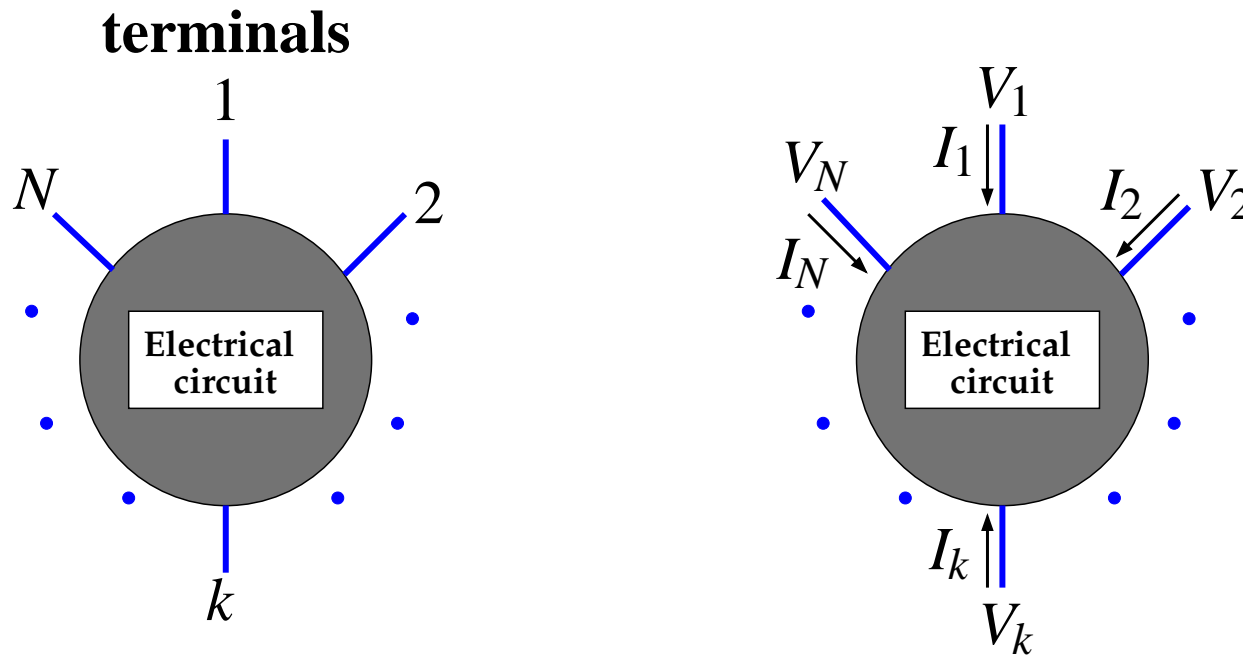


Not appropriate for describing the interaction of physical systems.

A physical system is not a signal processor.

SYSTEMS with TERMINALS

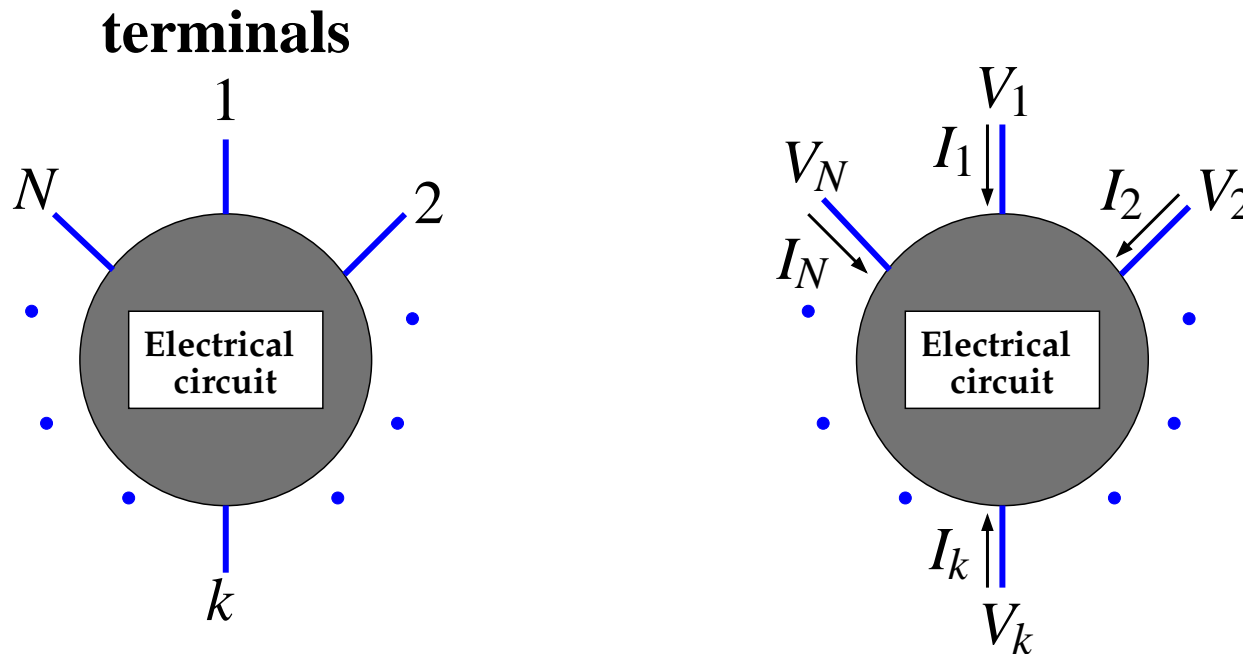
N-terminal circuit



At each terminal:

a **potential (!)** and a **current** (counted > 0 into the circuit),

N-terminal circuit



At each terminal:

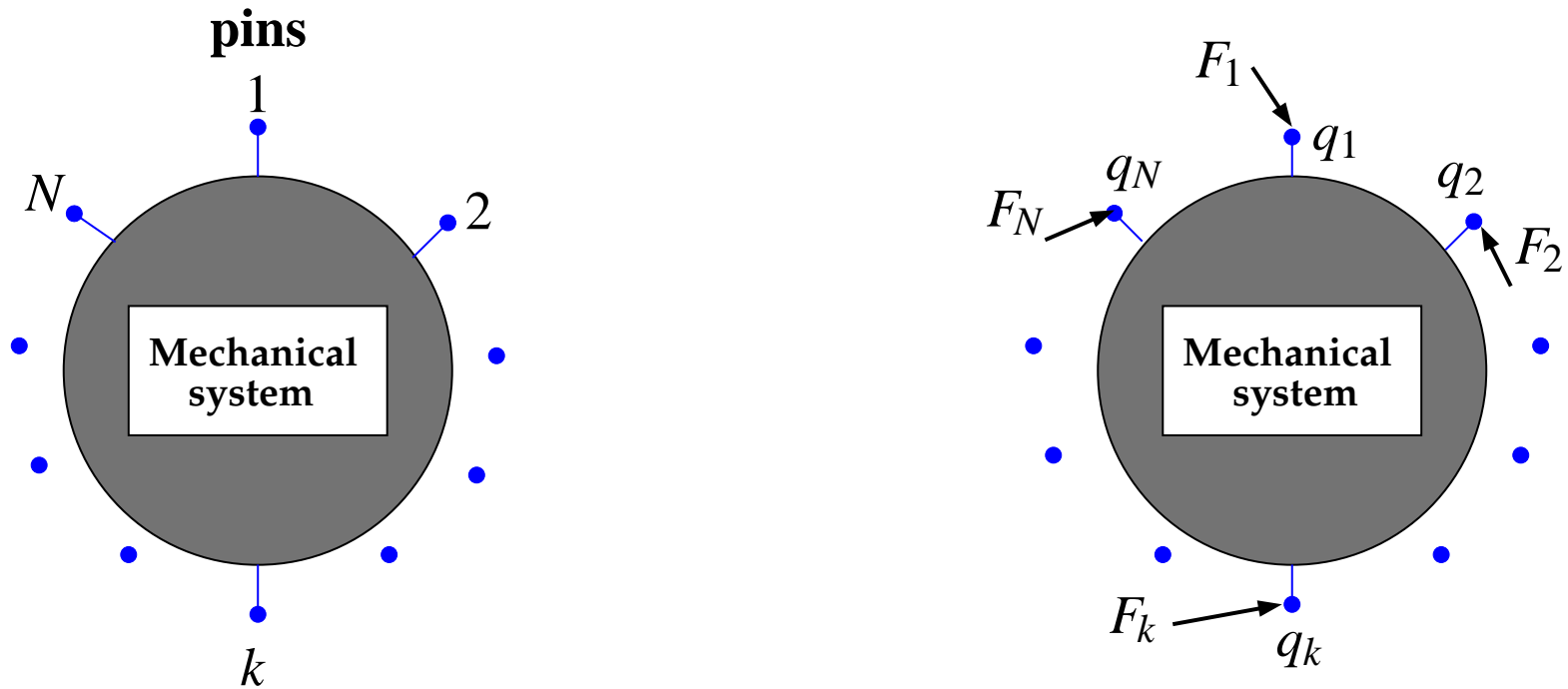
a **potential (!)** and a **current** (counted > 0 into the circuit),

\rightsquigarrow **behavior** $\mathcal{B} \subseteq (\mathbb{R}^N \times \mathbb{R}^N)^{\mathbb{R}}$.

$(V_1, V_2, \dots, V_N, I_1, I_2, \dots, I_N) \in \mathcal{B}$ means:

this potential/current trajectory is compatible with the circuit architecture and its element values.

Mechanical system



At each terminal: a **position** and a **force**.

\rightsquigarrow position/force trajectories $(q, F) \in \mathcal{B} \subseteq ((\mathbb{R}^\bullet)^{2N})^{\mathbb{R}}$.

More generally, a **position**, **force**, **angle**, and **torque**.

Systems

▶ Thermal systems:

At each terminal: a **temperature** and a **heat flow**.

▶ Hydraulic systems:

At each terminal: a **pressure** and a **mass flow**.

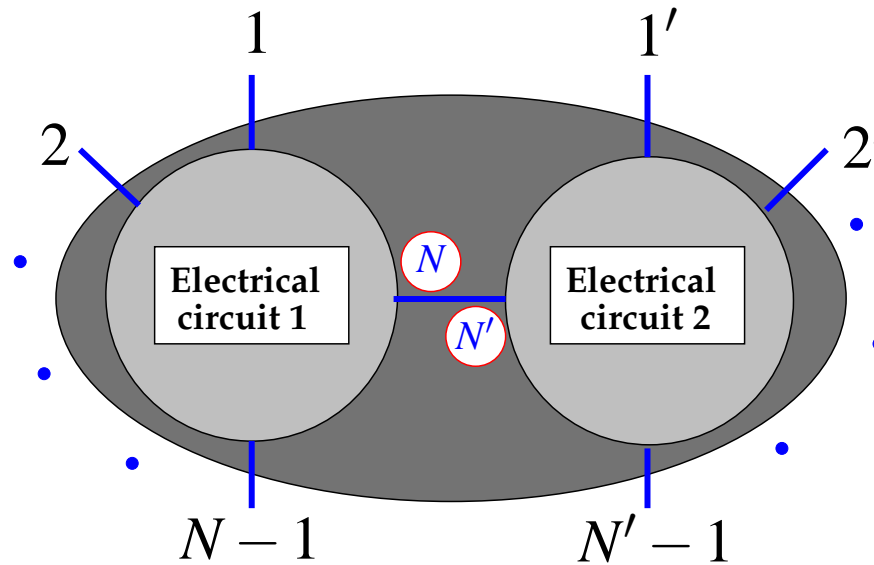
▶ Multidomain systems:

Systems with terminals of different types.

▶ ...

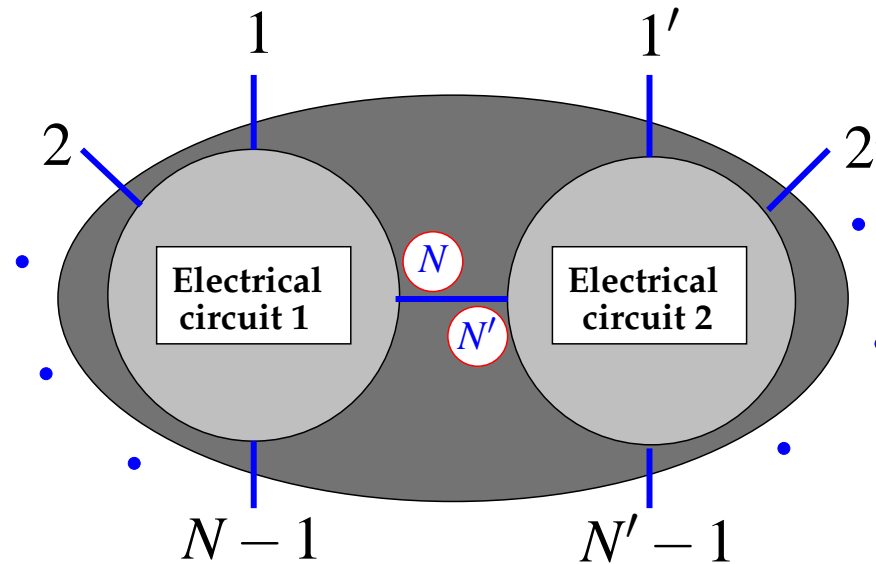
INTERCONNECTION

Interconnection of circuits



$$V_N = V_{N'} \quad \text{and} \quad I_N + I_{N'} = 0.$$

Interconnection of circuits



$$V_N = V_{N'} \quad \text{and} \quad I_N + I_{N'} = 0.$$

Behavior after interconnection:

$$\mathcal{B}_1 \sqcap \mathcal{B}_2$$

$$:= \left\{ (V_1, \dots, V_{N-1}, V_{1'}, \dots, V_{N'-1}, I_1, \dots, I_{N-1}, I_{1'}, \dots, I_{N'-1}) \mid \right.$$

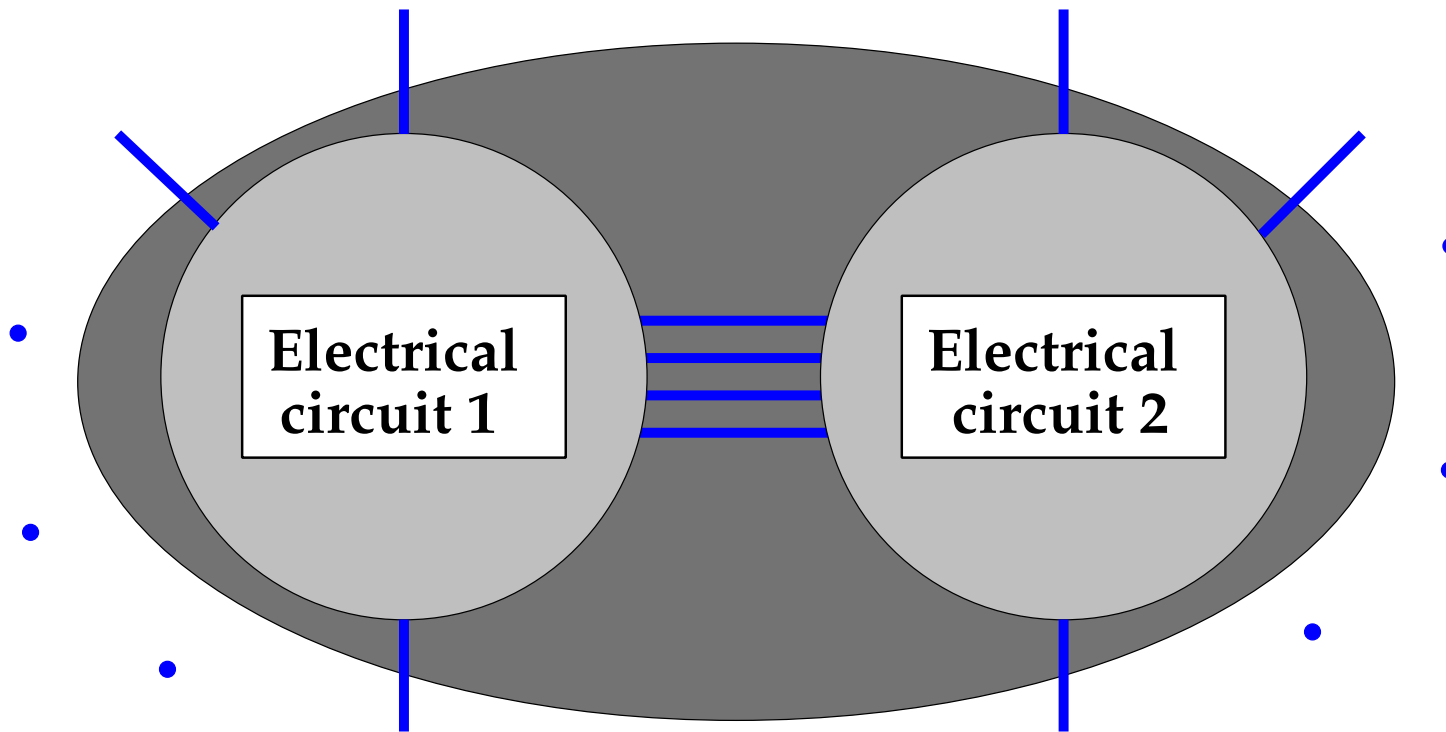
$\exists V, I$ such that

$$(V_1, \dots, V_{N-1}, V, I_1, \dots, I_{N-1}, I) \in \mathcal{B}_1 \quad \text{and}$$

$$(V_{1'}, \dots, V_{N'-1}, V, I_{1'}, \dots, I_{N'-1}, -I) \in \mathcal{B}_2 \}.$$

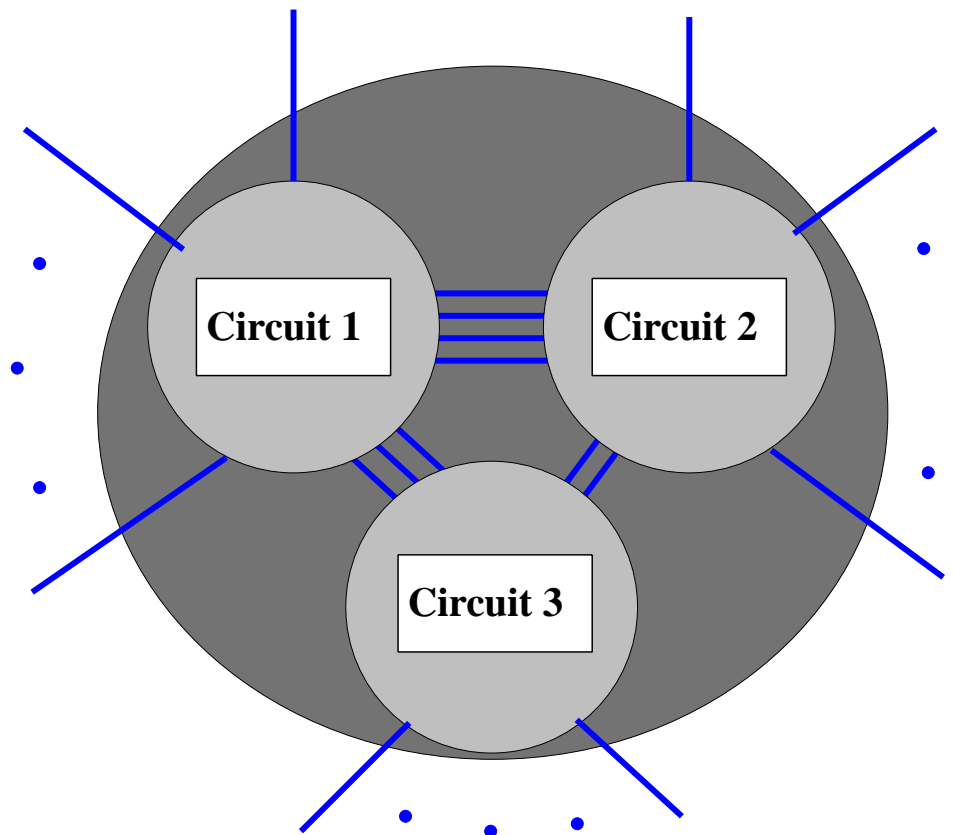
Interconnection of circuits

~> more terminals connected

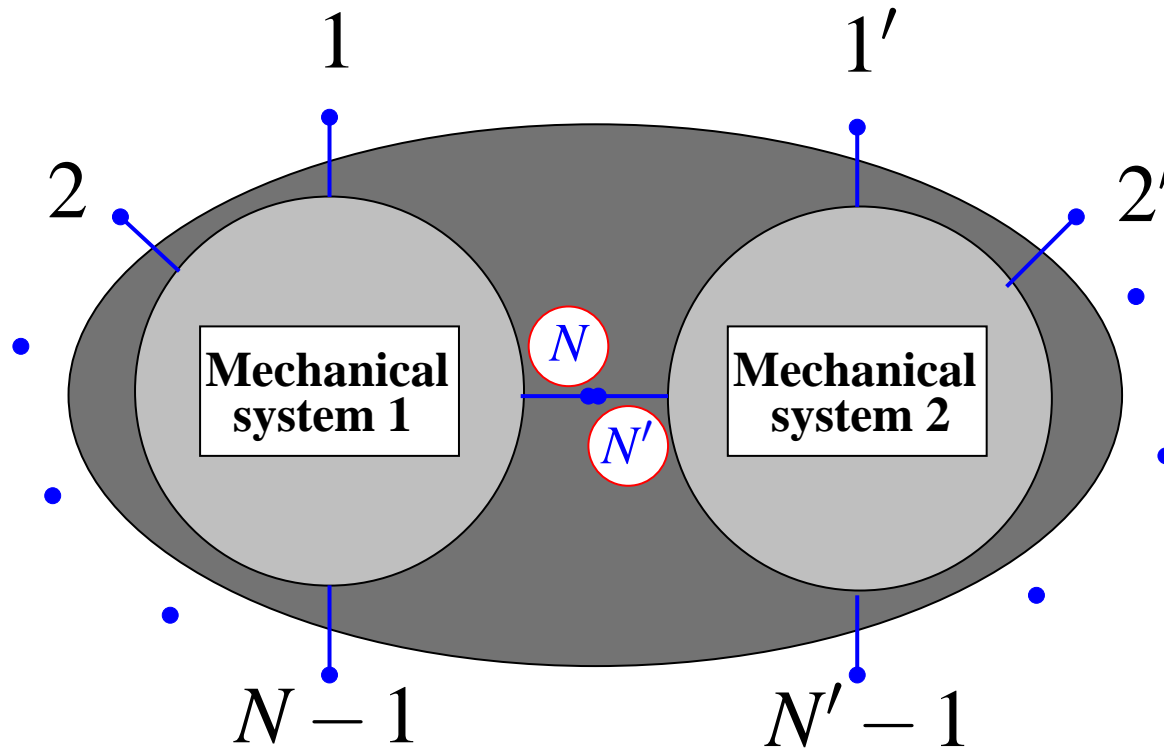


Interconnection of circuits

~> more circuits connected



Interconnection of mechanical systems



$$q_N = q_{N'} \quad \text{and} \quad F_N + F_{N'} = 0.$$

Other systems

▶ Thermal systems:

At each terminal: a temperature and a heat flow.

$$T_N = T_{N'} \quad \text{and} \quad Q_N + Q_{N'} = 0.$$

▶ Hydraulic systems:

At each terminal: a pressure and a mass flow.

$$p_N = p_{N'} \quad \text{and} \quad f_N + f_{N'} = 0.$$

▶ ...

Sharing variables

$$V_N = V_{N'} \quad \mathbf{and} \quad I_N + I_{N'} = 0,$$

$$q_N = q_{N'} \quad \mathbf{and} \quad F_N + F_{N'} = 0,$$

$$T_N = T_{N'} \quad \mathbf{and} \quad Q_N + Q_{N'} = 0,$$

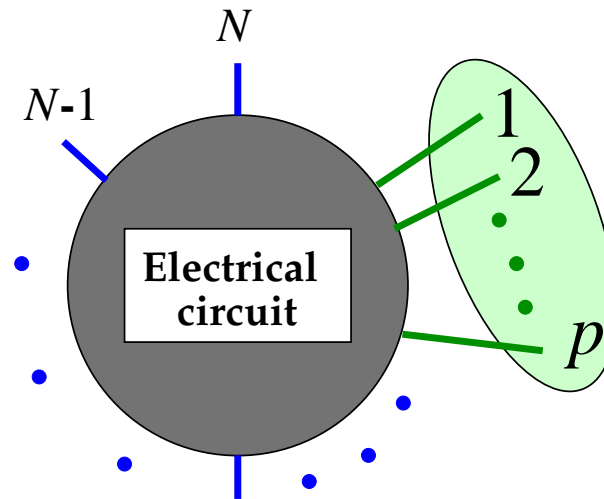
$$p_N = p_{N'} \quad \mathbf{and} \quad f_N + f_{N'} = 0,$$

⋮

Interconnection means variable sharing.

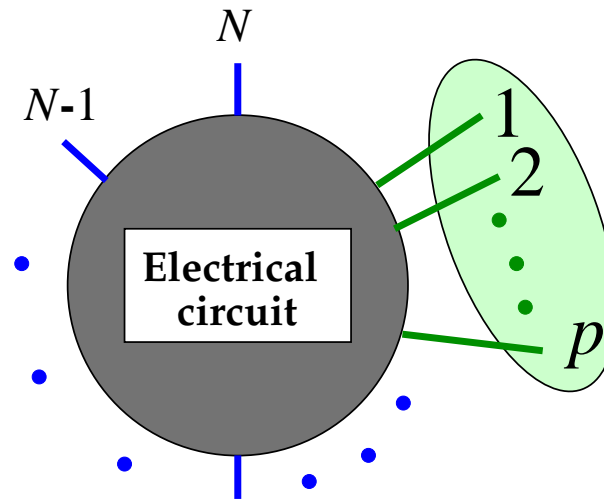
ENERGY TRANSFER

Ports



Terminals $\{1, 2, \dots, p\}$ form a **port** $:\Leftrightarrow$

Ports



Terminals $\{1, 2, \dots, p\}$ form a **port** $:\Leftrightarrow$

$(V_1, \dots, V_p, V_{p+1}, \dots, V_N, I_1, \dots, I_p, I_{p+1}, \dots, I_N) \in \mathcal{B}, \alpha : \mathbb{R} \rightarrow \mathbb{R}$

$\Rightarrow (V_1 + \alpha, \dots, V_p + \alpha, V_{p+1}, \dots, V_N, I_1, \dots, I_p, I_{p+1}, \dots, I_N) \in \mathcal{B}$

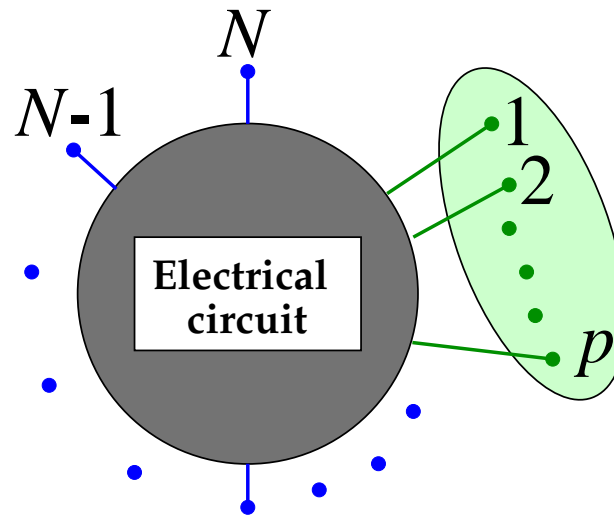
and $I_1 + \dots + I_p = 0$.

'port KVL'

and

'port KCL'.

Ports



If terminals $\{1, 2, \dots, p\}$ form a port, then

power in along these terminals = $V_1(t)I_1(t) + \dots + V_p(t)I_p(t)$,

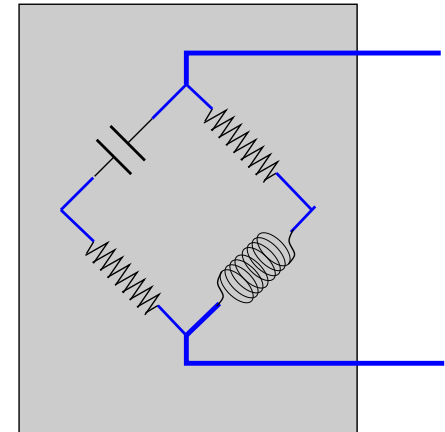
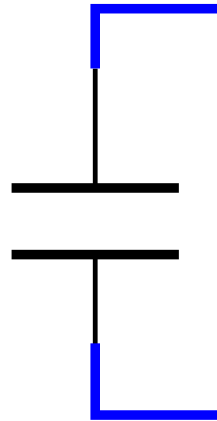
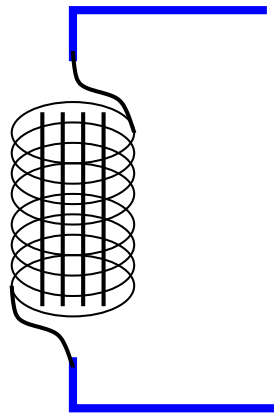
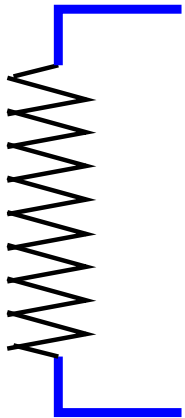
energy in = $\int_{t_1}^{t_2} (V_1(t)I_1(t) + \dots + V_p(t)I_p(t)) dt$.

This interpretation in terms of power and energy is not valid unless these terminals form a port !

Examples

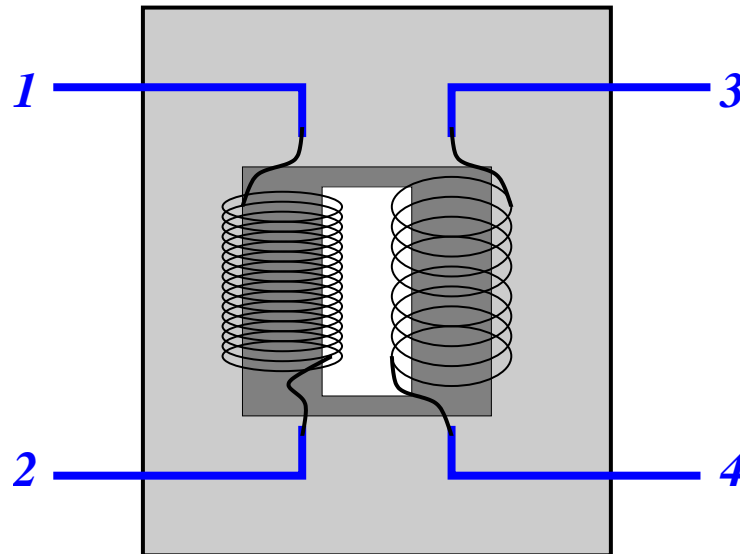
Examples of 1-port 2-terminal devices:

**resistors, capacitors, inductors, memristors,
any 2-terminal circuit composed of these.**



Examples

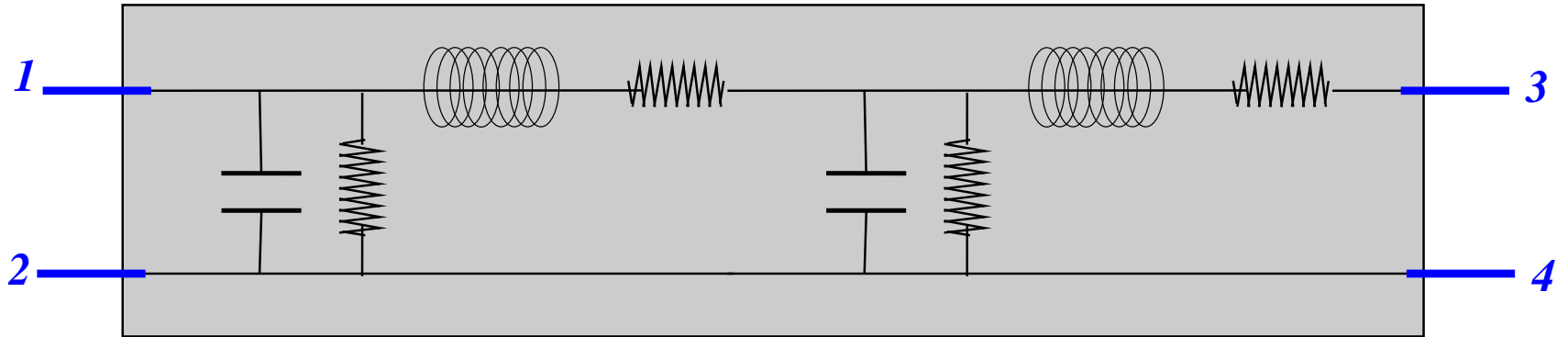
Example of 2-port 4-terminal device:



$$V_1 - V_2 = n(V_3 - V_4), \quad -nI_1 = I_3 \quad I_1 + I_2 = 0, I_3 + I_4 = 0$$

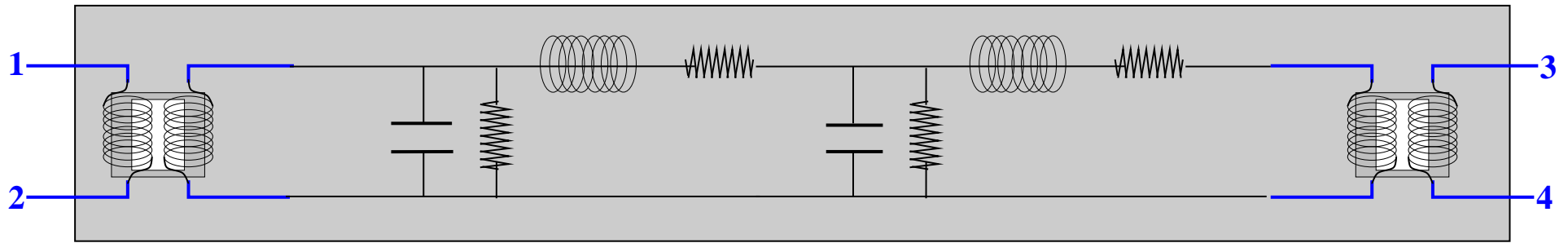
Terminals $\{1, 2\}$ and $\{3, 4\}$ (and $\{1, 2, 3, 4\}$) form ports.

Examples

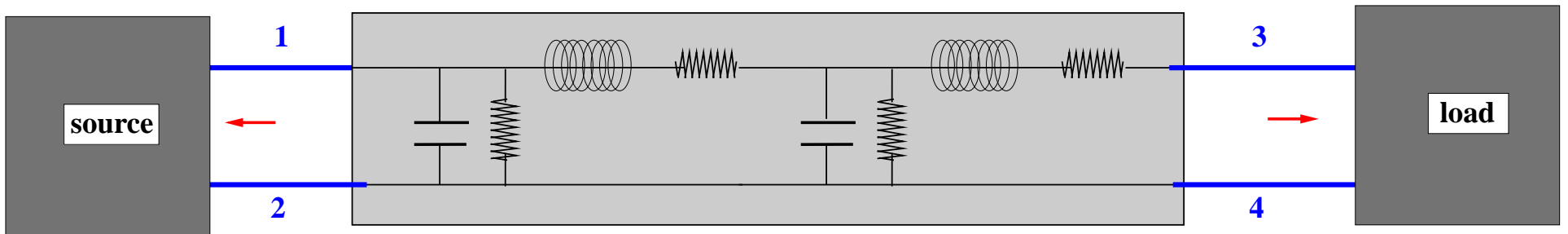


Terminals $\{1, 2, 3, 4\}$ form a port. But $\{1, 2\}$ and $\{3, 4\}$ do not.

Examples

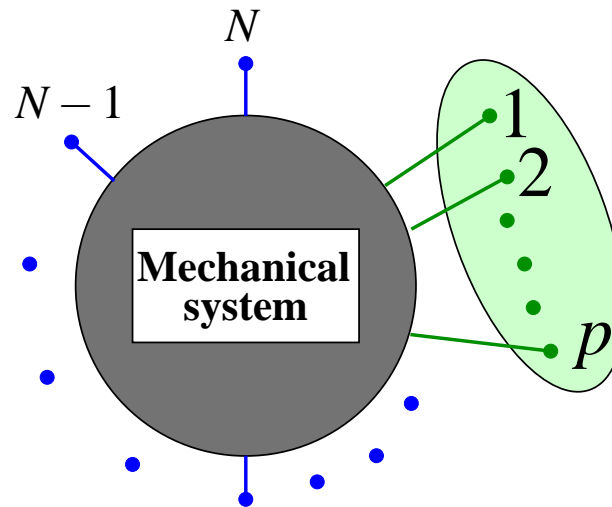


Terminals $\{1, 2\}$ and $\{3, 4\}$ form a port.



Terminals $\{1, 2\}$ and $\{3, 4\}$ form 'internal' ports.

Mechanical ports



Terminals $\{1, 2, \dots, p\}$ form a (mechanical) port $:\Leftrightarrow$

$$(q_1, \dots, q_p, q_{p+1}, \dots, q_N, F_1, \dots, F_p, F_{p+1}, \dots, F_N) \in \mathcal{B},$$

and $v : t \in \mathbb{R} \mapsto (a + bt) \in \mathbb{R}^\bullet$, **with** $a, b \in \mathbb{R}^\bullet$

$$\Rightarrow (q_1 + v, \dots, q_p + v, q_{p+1}, \dots, q_N, F_1, \dots, F_p, F_{p+1}, \dots, F_N) \in \mathcal{B}$$

and $F_1 + F_2 + \dots + F_p = 0.$

'invariance under uniform motion' and *'KFL'*.

Power and energy

If terminals $\{1, 2, \dots, p\}$ form a port, then

$$\text{power in} = F_1(t)^\top \frac{d}{dt} q_1(t) + \dots + F_p(t)^\top \frac{d}{dt} q_p(t),$$

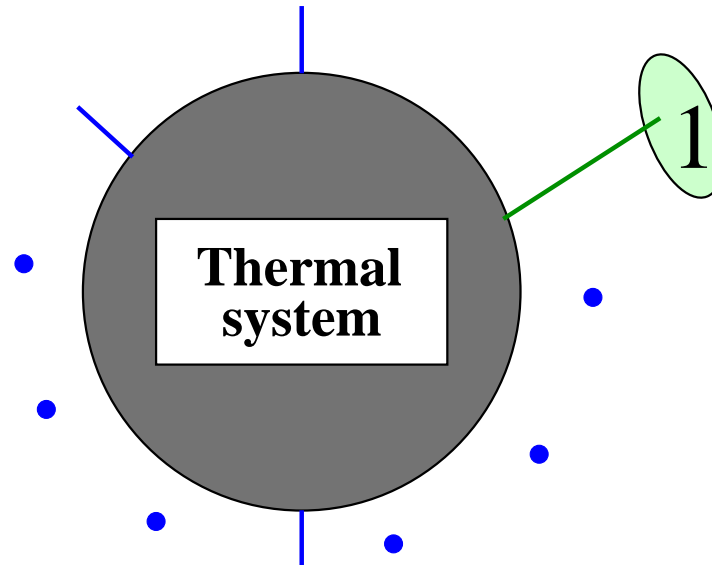
and

$$\text{energy in} = \int_{t_1}^{t_2} \left(F_1(t)^\top \frac{d}{dt} q_1(t) + \dots + F_p(t)^\top \frac{d}{dt} q_p(t) \right) dt.$$

**This interpretation in terms of power and energy is not valid
unless these terminals form a port !**

Other domains

temperature T , heat flow Q



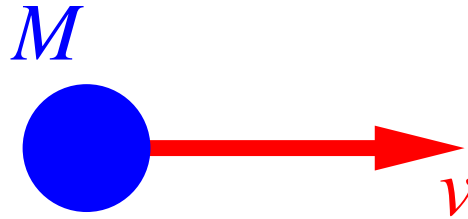
- ▶ Thermal systems: Every terminal forms a port.

$$\text{power in} = Q_1(t).$$

- ▶ ...

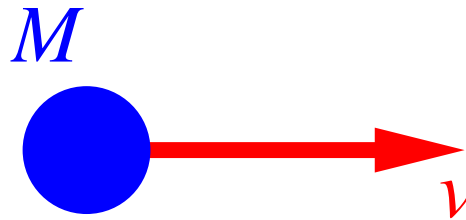
KINETIC ENERGY

Kinetic energy and invariance under uniform motions



What is the kinetic energy?

Kinetic energy and invariance under uniform motions



What is the kinetic energy?

$$\mathcal{E}_{\text{kinetic}} = \frac{1}{2} M ||v||^2$$



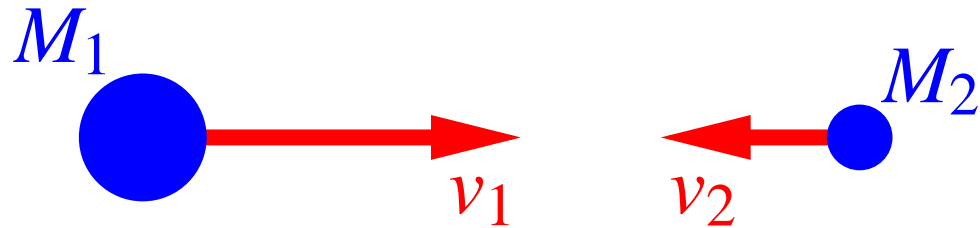
Willem 's Gravesande
1688–1742



Émilie du Châtelet
1706–1749

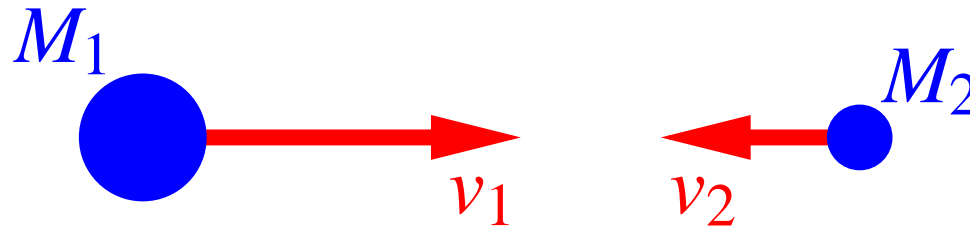
This formula is not invariant under uniform motion.

Kinetic energy and invariance under uniform motions



What is the kinetic energy?

Kinetic energy and invariance under uniform motions



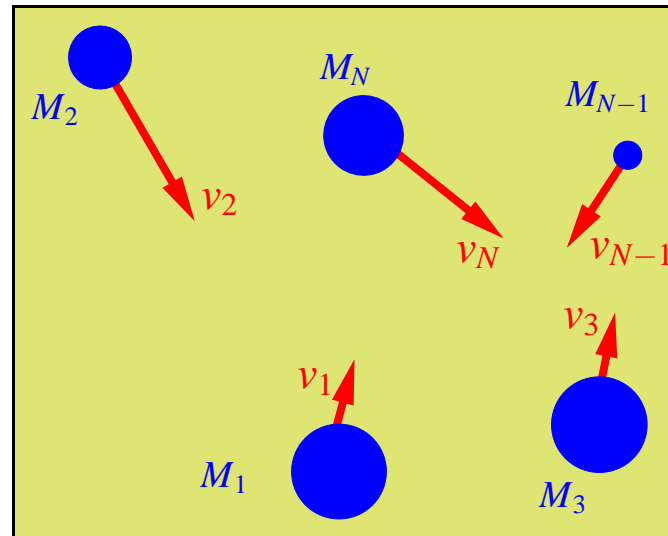
What is the kinetic energy?

$$\mathcal{E}_{\text{kinetic}} = \frac{1}{2} \frac{M_1 M_2}{M_1 + M_2} \|v_1 - v_2\|^2$$

Invariant under uniform motion.

Can be justified by mounting a damper or a spring between the masses.

Kinetic energy

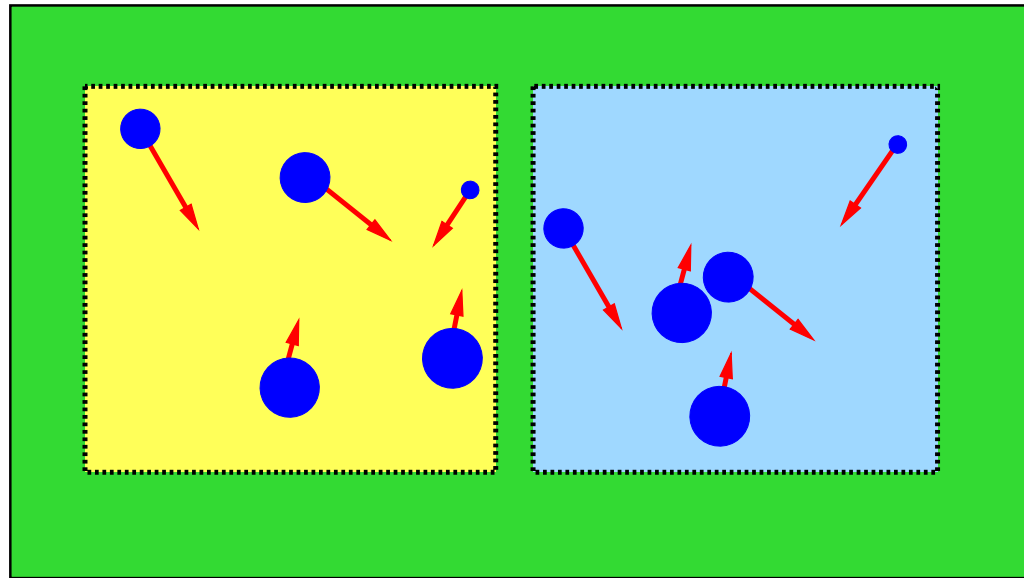


$$\mathcal{E}_{\text{kinetic}} = \frac{1}{4} \sum_{i,j \in \{1,2,\dots,N\}} \frac{M_i M_j}{M_1 + M_2 + \dots + M_N} \|v_i - v_j\|^2.$$

$$\mathbf{KFL} \Rightarrow \frac{d}{dt} \mathcal{E}_{\text{kinetic}} = \sum_{i \in \{1,2,\dots,N\}} F_i^\top v_i.$$

Kinetic energy

Kinetic energy is not additive.



Total kinetic energy \neq sum of the parts.

Kinetic energy

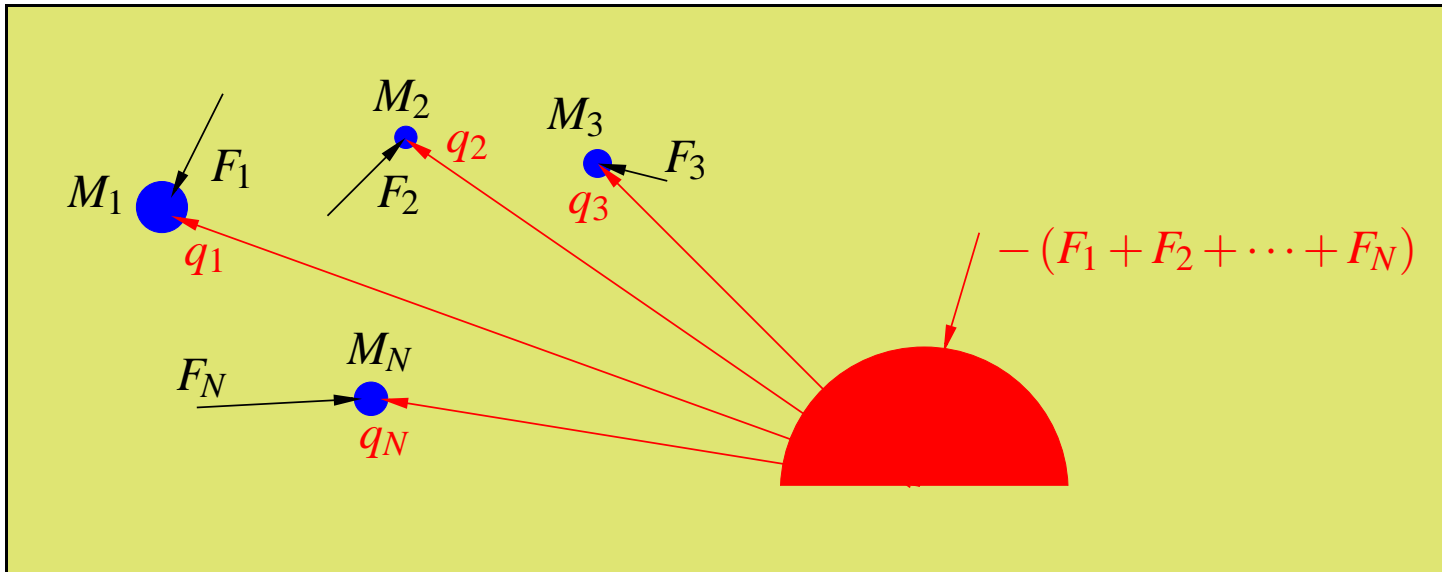
$$\mathcal{E}_{\text{kinetic}} = \frac{1}{4} \sum_{i,j \in \{1,2,\dots,N\}} \frac{M_i M_j}{M_1 + M_2 + \dots + M_N} \|v_i - v_j\|^2.$$

Distinct from the classical expression of the kinetic energy,

$$\mathcal{E}_{\text{classical}} = \frac{1}{2} \sum_{i \in \{1,2,\dots,N\}} M_i \|v_i\|^2.$$

Kinetic energy

Reconciliation: $M_{N+1} = \infty, F_{N+1} = -(F_1 + F_2 + \dots + F_N),$



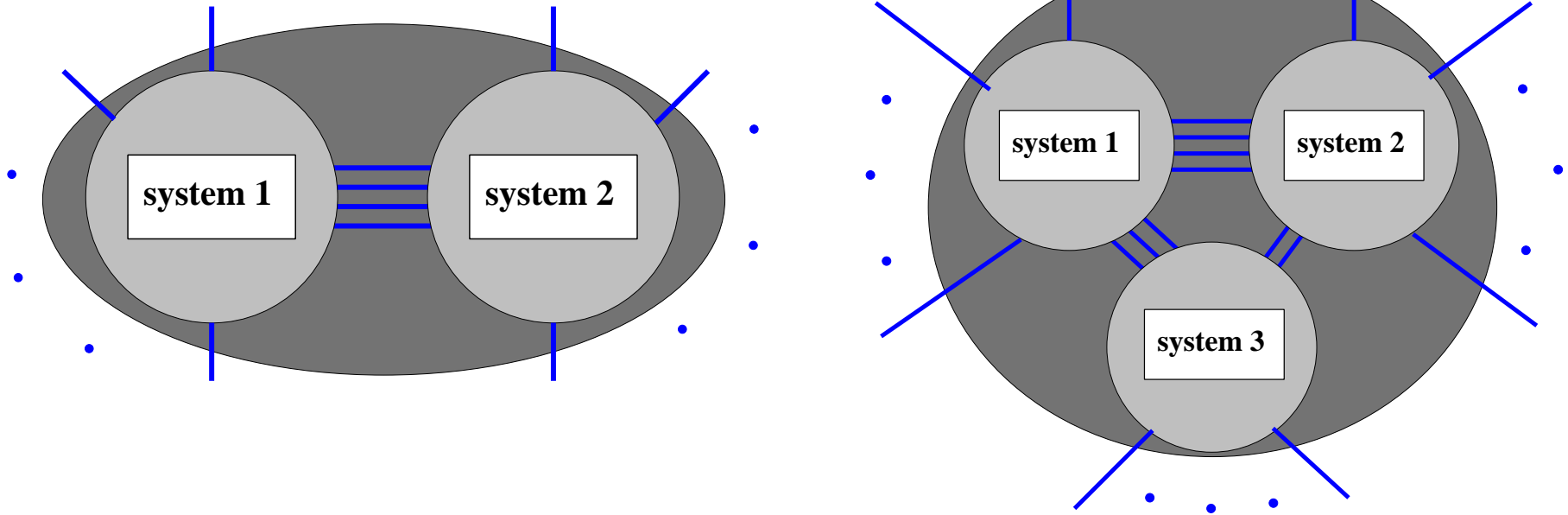
measure velocities w.r.t. this infinite mass, then

$$\frac{1}{4} \sum_{i,j \in \{1,2,\dots,N,N+1\}} \frac{M_i M_j}{M_1 + M_2 + \dots + M_N + M_{N+1}} \|v_i - v_j\|^2$$

$$\longrightarrow \frac{1}{2} \sum_{i \in \{1,2,\dots,N\}} M_i \|v_i\|^2.$$

PORTS and TERMINALS

Energy transfer

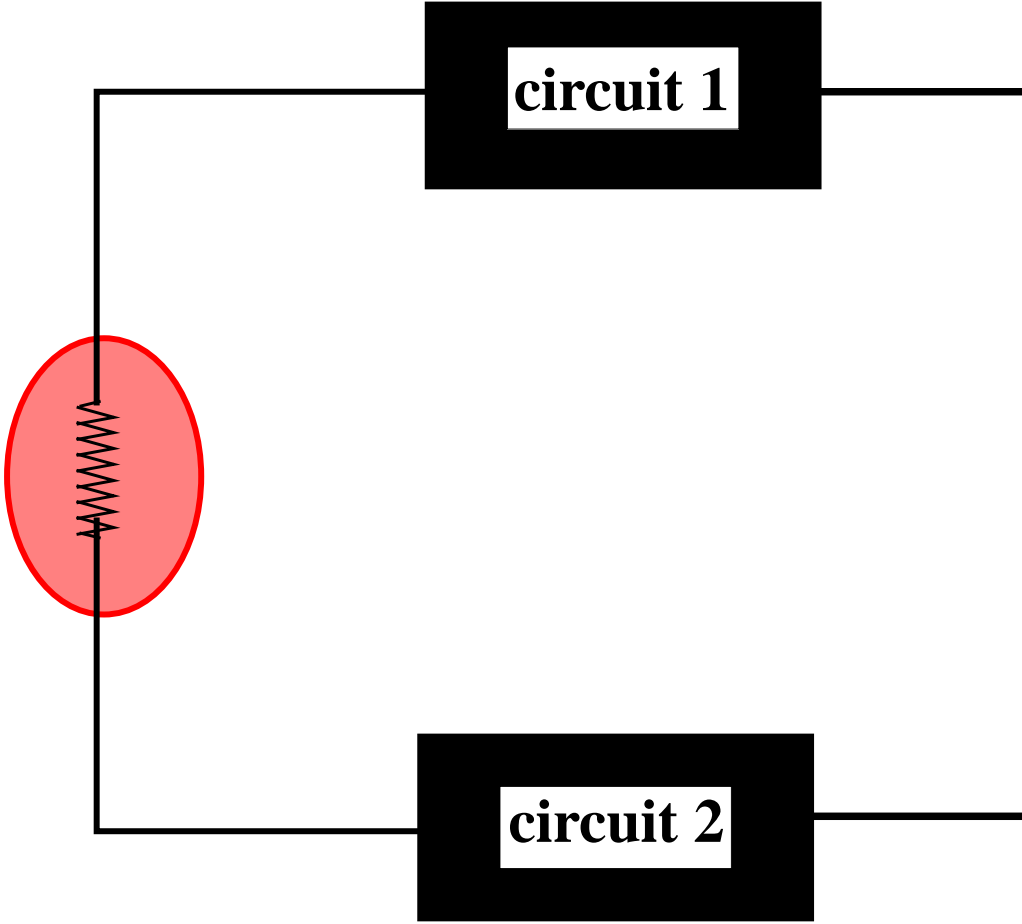


One cannot speak about

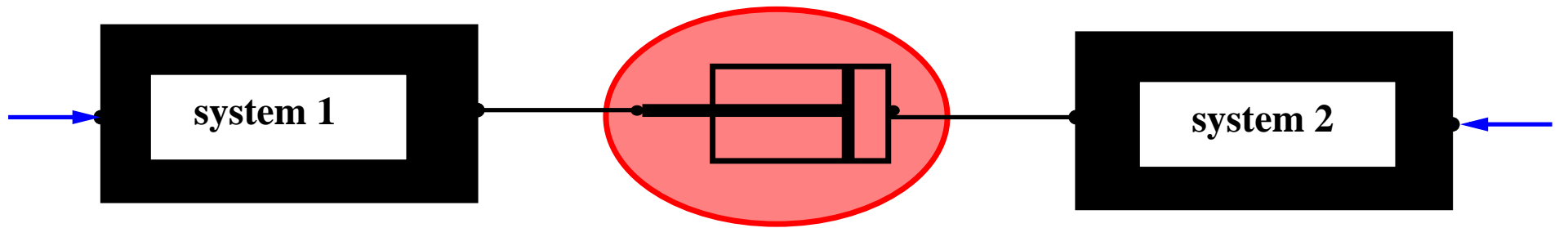
*“the energy transferred from system 1 to system 2”
or “from the environment to system 1”,*

unless the relevant terminals form a port.

Energy transfer



Energy transfer



Terminals and ports

Terminals are for interconnection, ports are for energy transfer.

**Interconnection is 'local',
power and energy transfer involve 'action at a distance'.**

Terminals and ports

Terminals are for interconnection, ports are for energy transfer.

**Interconnection is ‘local’,
power and energy transfer involve ‘action at a distance’.**

**The basis of bond-graph (and related) modeling
methodologies that**

*‘In physical systems, the interaction between subsystems
is always related to an exchange of energy’*

is flawed.

CONCLUSION

Interconnection

- ▶ **Physical systems are not input/output devices. Interconnection of physical systems should not be viewed in terms of output-to-input assignment.**

A physical system is not a signal processor.

Interconnection

- ▶ **Physical systems are not input/output devices. Interconnection of physical systems should not be viewed in terms of output-to-input assignment.**

A physical system is not a signal processor.

- ▶ **Interconnection of physical devices is distinctly different from equating power and energy flow.**

Interconnection is ‘local’,

power and energy involve ‘action at a distance’.

Interconnection

- ▶ **Physical systems are not input/output devices. Interconnection of physical systems should not be viewed in terms of output-to-input assignment.**

A physical system is not a signal processor.

- ▶ **Interconnection of physical devices is distinctly different from equating power and energy flow.**

Interconnection is ‘local’,

power and energy involve ‘action at a distance’.

- ▶ **Interconnection of physical systems involves variable sharing.**



Geniet van jouw emeritaat !!!

**The behavioral approach to open and interconnected systems,
Control Systems Magazine, volume 27, pages 46-99, 2007.**

Copies of the lecture frames will be available from/at

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<http://www.esat.kuleuven.be/~jwillems>

Thank you

Thank you

Thank you

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