Energy Management for Building Climate Comfort in Uncertain STGs with ATES

Vahab Rostampour, and Tamás Keviczky

Delft Center of Systems and Control Delft University of Technology

> July 9-14, 2017 IFAC World Congress Toulouse, France





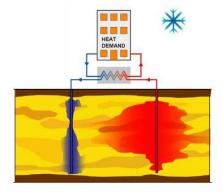


Aquifer Thermal Energy Storage (ATES)

- A large-scale natural subsurface storage for thermal energy
- · An innovative method for thermal energy balance in smart grids

Cold season:

- The building requests thermal energy for heating purpose
- Water is injected into cold well and is taken from warm well
- The stored water contains cold thermal energy for next season



[Rostampour et al., JEP, 2016]

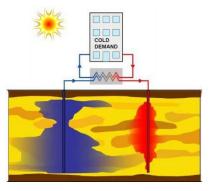
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Aquifer Thermal Energy Storage (ATES)

- A large-scale natural subsurface storage for thermal energy
- · An innovative method for thermal energy balance in smart grids

Warm season:

- The building requests thermal energy for cooling purpose
- Water is injected into warm well and is taken from cold well
- The stored water contains warm thermal energy for next season



[Rostampour et al., JEP, 2016]

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How to Deal with ATES Systems in Smart Thermal Grids?

[Ma, et al., TCS 2015] [Ma, et al., CDC 2009] [Nghiem, Jones, ACC 2017] [Taha Ahmad, et al., ArXiv 2017]

and a lot more!!!

Building Climate Comfort Control

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Building Climate Comfort Control

[Ooteghem, PhD Thesis 2007] No static/dynamic model !!! assumed that given infinity available energy storage

There are no more works to best of our knowledge!!!

> ATES System

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Stochastic MPC

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How to deal with a network of interconnected buildings subject to private (local) uncertainty source and common uncertain pool (ATES systems) !!!

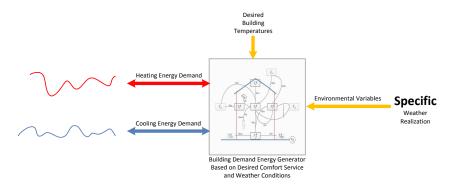
[Calafiore, Campi, TAC 2006] [Campi, Garatti SIAM 2008] [Margellos, Rostampour, et al., ECC, 2013] [Zhang, et al., CDC 2013] [Margellos, Goulart and Lygeros, TAC 2016] [Rostampour, Keviczky, ECC, 2016] and a lot more!!!

Stochastic MPC

1 Single Building with ATES System Dynamics

- 2 ATES Smart Thermal Grids: Common Resource Pool
- **3** Probabilistic Energy Management Framework
- G Simulation Study: Utrecht City Case Study
- **5** Concluding Remarks and Future Work

Single Building Thermal Energy Demand



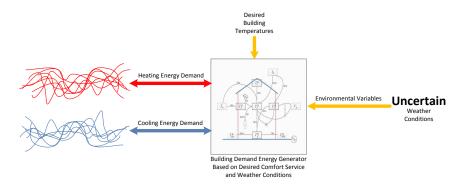
Thermal Energy Demand Profile:

- Complete and detailed building dynamical model
- Desired building temperatures (local controller unit)
- In specific weather realization, certain demand profiles are generated

[Rostampour & Keviczky, ECC, 2016]

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Single Building Thermal Energy Demand



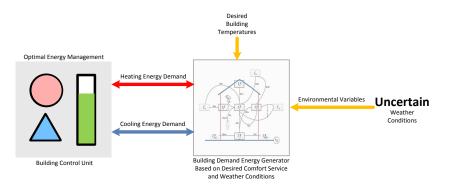
Thermal Energy Demand Profile:

- Complete and detailed building dynamical model
- Desired building temperatures (local controller unit)
- In uncertain conditions, uncertain demand profiles are generated

[Rostampour & Keviczky, ECC, 2016]

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Single Building Climate Comfort System



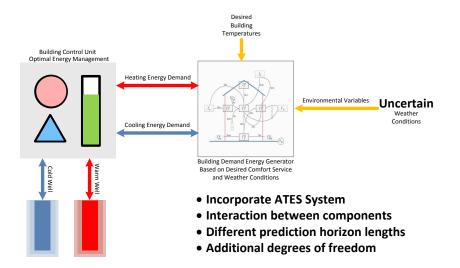
Building Control Unit:

- Main components: Boiler, HP, HE, micro-CHP, Storage Tank
- ON/OFF status together with production schedule as decisions
- Control Objective: thermal energy balance for the overall systems

[Rostampour & Keviczky, ECC, 2016]

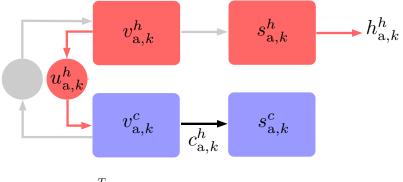
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Building Climate Comfort and ATES Systems



ATES System Dynamics: Control Block Diagram

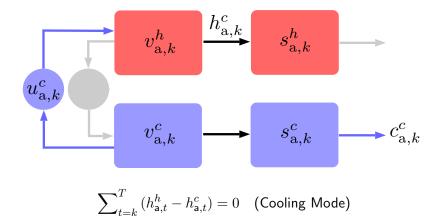
An important operational limitation of ATES system is that the sum of injected and extracted thermal energy over a period of time has to be zero.



$$\sum_{t=k}^{I} (c_{\mathsf{a},t}^{h} - h_{\mathsf{a},t}^{h}) = 0 \quad \text{(Heating Mode)}$$

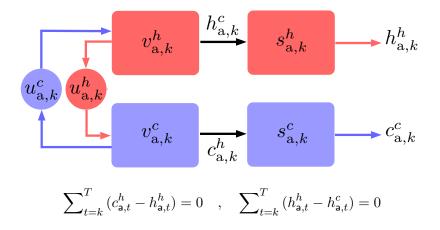
ATES System Dynamics: Control Block Diagram

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ATES System Dynamics: Control Block Diagram

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Energy Balance between Wells of ATES

Proposed Constraint Reformulation

Given \bar{s}_{a} the initial amount of stored thermal energy in ATES system, then the following reformulation is exact.

$$\left(\mathbf{I} \right) \begin{array}{l} \sum_{t=k}^{T} \left(c_{\mathsf{a},t}^{h} - h_{\mathsf{a},t}^{h} \right) &= 0 \\ \sum_{t=k}^{T} \left(h_{\mathsf{a},t}^{h} - h_{\mathsf{a},t}^{c} \right) &= 0 \end{array} \right\} \quad \Leftrightarrow \quad s_{\mathsf{a},T}^{h} + s_{\mathsf{a},T}^{c} = \bar{s}_{\mathsf{a}} \quad (\mathsf{II})$$

Note that the constraint (II) should be imposed as a terminal constraint.

• Proposed constraint is softened using $e_{i,t}$ as an auxiliary variable:

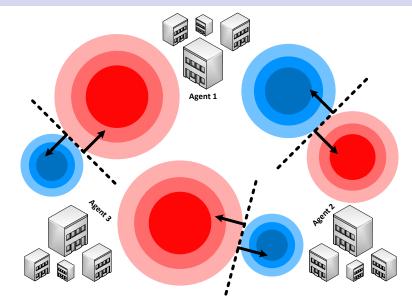
$$s_{\mathsf{a},T}^h + s_{\mathsf{a},T}^c \le \bar{s}_{\mathsf{a}} + e_{i,T} \quad , \quad s_{\mathsf{a},T}^h + s_{\mathsf{a},T}^c \ge \bar{s}_{\mathsf{a}} - e_{i,T}$$

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ATES Systems in STGs



How to Avoid Interactions Between Neighboring Wells?

Problem: Nonconvex constraint formulation!

One can now restrict the thermal radius between the neighboring agents:

$$(r_{\mathsf{a},t}^h)_i + (r_{\mathsf{a},t}^c)_j \le d_{ij}$$

where d_{ij} is a given distance between the neighboring agents i, j.

Proposed convex constraint reformulation

Given $\delta_{ij,t} = 2c_{aq}\pi\ell (\bar{r}^{h}_{a,t})_i (\bar{r}^{c}_{a,t})_j/c_{pw}$ as a common uncertainty source between the neighboring agents i, j, then we propose the following linear (convex) constraint:

$$(v_{\mathsf{a},t}^h)_i + (v_{\mathsf{a},t}^c)_j \le \bar{v}_{ij} - \delta_{ij,t}$$

where $\bar{v}_{ij}=\frac{c_{aq}}{c_{pw}}\pi\ell\,d_{ij}^2$ is an upper-bound on the capacity of common resource pool.

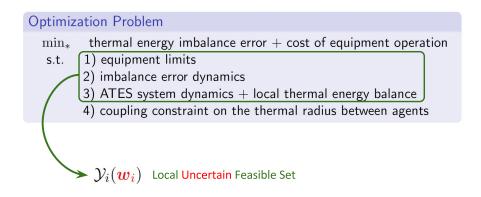
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Optimization Problem

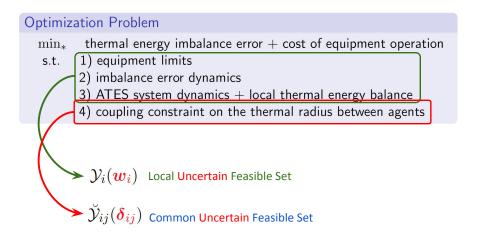
\min_{\ast} \quad thermal energy imbalance error + cost of equipment operation

- s.t. 1) equipment limits
 - 2) imbalance error dynamics
 - 3) ATES system dynamics + local thermal energy balance
 - 4) coupling constraint on the thermal radius between agents

*set-points for control units of buildings and pump flow rate for ATES systems



^{*}set-points for control units of buildings and pump flow rate for ATES systems



 $\ensuremath{^*\text{set-points}}$ for control units of buildings and pump flow rate for ATES systems

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Compact Uncertain Program: decision variables $\boldsymbol{y} = (\boldsymbol{y}_1, \cdots, \boldsymbol{y}_i, \cdots)$

$$egin{aligned} \min_{oldsymbol{y}} & \sum_i f_i(oldsymbol{y}_i) \ ext{s.t.} & oldsymbol{y} \in \prod_i \mathcal{Y}_i(oldsymbol{w}_i) \;, \ & oldsymbol{y} \in \prod_i igcap_i ec{\mathcal{Y}}_{ij}(oldsymbol{\delta}_{ij}) \end{aligned}$$

Stochastic Optimization Problem

$$\begin{split} \min_{\boldsymbol{y}} & \sum_{i} f_{i}(\boldsymbol{y}_{i}) \\ \text{s.t.} & \mathbb{P}_{\boldsymbol{w}}\Big[\boldsymbol{y} \in \prod_{i} \mathcal{Y}_{i}(\boldsymbol{w}_{i})\Big] \geq 1 - \varepsilon \;, \forall \boldsymbol{w} \in \mathcal{W} \\ & \mathbb{P}_{\boldsymbol{\delta}}\Big[\boldsymbol{y} \in \prod_{i} \bigcap_{j} \breve{\mathcal{Y}}_{ij}(\boldsymbol{\delta}_{ij})\Big] \geq 1 - \bar{\varepsilon} \;, \forall \boldsymbol{\delta} \in \Delta \end{split}$$

Stochastic Setting:

- \mathcal{W}, Δ : Possibly unknown distribution and unbounded set
- Multiple chance constraints mixed-integer optimization
- Semi-infinite optimization problem

Using two-step (robust-randomized) approach¹:

- Determining a bounded set that contains $1-ar{arepsilon}$ portion of Δ
- Solving the robust counterpart of problem w.r.t. the bounded set \mathcal{S}^*



¹[Margellos, Rostampour, et al., ECC, 2013], [Rostampour & Keviczky, ECC, 2016]

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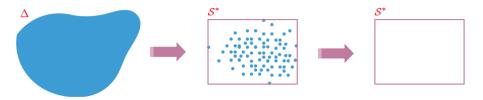
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Multi-Robust-Randomized Optimization Problem

$$\begin{split} \min_{\boldsymbol{y}} & \sum_{i} f_{i}(\boldsymbol{y}_{i}) \\ \text{s.t.} & \boldsymbol{y} \in \bigcap_{\boldsymbol{w} \in \{\mathcal{S}^{*} \cap \mathcal{W}\}} \prod_{i} \mathcal{Y}_{i}(\boldsymbol{w}_{i}) , \\ & \boldsymbol{y} \in \bigcap_{\boldsymbol{\delta} \in \{\bar{\mathcal{S}}^{*} \cap \Delta\}} \prod_{i} \bigcap_{j} \breve{\mathcal{Y}}_{ij}(\boldsymbol{\delta}_{ij}) \end{split}$$

Multi-Robust-Randomized Optimization Problem

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Requirements

$$\mathcal{W} = \prod_{i} \mathcal{W}_{i} \quad \Delta = \prod_{i} \Delta_{i} \quad \Delta_{i} = \prod_{j} \Delta_{ij}$$
$$\mathcal{S}^{*} = \prod_{i} \mathcal{S}^{*}_{i} \quad \bar{\mathcal{S}}^{*} = \prod_{i} \bar{\mathcal{S}}^{*}_{i} \quad \bar{\mathcal{S}}^{*}_{i} = \prod_{j} \bar{\mathcal{S}}^{*}_{ij}$$

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Multi-Robust-Randomized Approach

Probabilistically Feasible Solutions

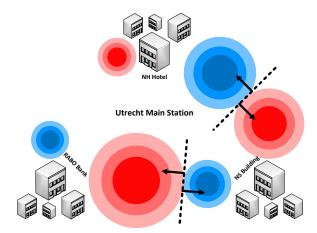
The obtained solution via our proposed scheme is a feasible solution for each chance constraint with their desired level of violations and confidence.

Steps of proof:

- 1 Based on the scenario approach in [Calafiore & Campi, TAC 2006]
- 2 Following the similar steps in [Margellos, Goulart & Lygeros, TAC 2016]
- **③** Extending to the multiple chance constraints

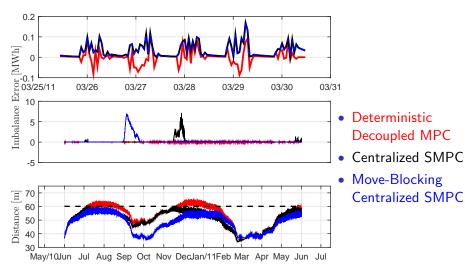
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STGs with ATES Systems: Utrecht City Case Study

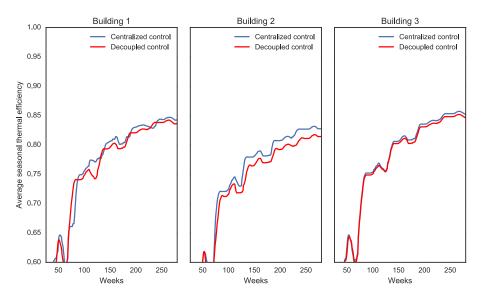


- Three buildings in Utrecht city with real parameters
- Real weather condition data from 2010 to 2012

Simulations Results: A-Posteriori Feasibility Validation



Geohydrological Simulation Environment (MODFLOW)



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• A practical predictive dynamical model of ATES system

 \Rightarrow local energy balance constraint \Rightarrow mutual interaction avoidance

- Pros we can use such a model to predict behavior of the new installed/completely depleted ATES system
- Cons such a model is a stochastic hybrid system (nonconvex program) and this leads sub-optimal performance
- Simulation results showed expected behavior

What comes next?

1 Distributed Stochastic Hierarchical MPC

- higher layer to manage ATES systems in STGs
- lower layer to provide desired comfort level for building control systems
- 2 Distributed Stochastic MPC in a Plug-and-Play Framework
 - Rostampour, Keviczky, Submitted.

Thank you for your attention! Questions?

Contact at: http://www.dcsc.tudelft.nl/~vrostampour/ v.rostampour@tudelft.nl

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