

## List of errata for the lecture notes

### Modeling and Control of Hybrid Systems (edition: January 2009)

Errata version 0.1 — February 8, 2010

- p. ix** Line -5: Replace “rows” by “columns” and replace “ $I$ ” by “ $J$ ”.
- p. ix** Line -4: Replace “ $\mathbb{R}^{n \times m}$ ” by “ $\mathbb{R}^{m \times n}$ ”.
- p. 1** Line 1: Remove the second “like” in “like a like”.
- p. 24** Line 2 after Figure 1.17: Replace “ $q2$ ” by “ $q_2$ ”.
- p. 24** Line 3 after Figure 1.17: Replace “ $q1$ ” by “ $q_1$ ” and remove the dot at the end of the equation.
- p. 24** Line 4 after Figure 1.17: Replace “as” by “since” and “tanks” by “tank”.
- p. 31** Rewrite (2.20) as follows: “ $10\delta(k) \leq x(k) + 10$ ”.  
Rewrite (2.21) as follows: “ $(-10 - \varepsilon)\delta(k) \leq -x(k) - \varepsilon$ ”.
- p. 49** Line -3: Put “[...]” around “ $\frac{d\phi}{dx}(x(t))$ ”. So “ $\frac{d\phi}{dt}(x(t)) = \left[\frac{d\phi}{dx}(x(t))\right]^T \dot{x}(t) = \dots$ ”.
- p. 51** Line 11 after (3.6): Replace “ $\{x_k\}_{k \in \mathbb{N}}$ ” by “ $\{x_k\}_{k=0}^\infty$ ”.  
Line 12 after (3.6): Replace “ $\lim_{k \rightarrow}$ ” by “ $\lim_{k \rightarrow \infty}$ ”.
- p. 70** Line 4 of Theorem 4.3.4: Replace “ $\frac{\partial V}{\partial x}$ ” by “ $\left[\frac{\partial V}{\partial x}\right]^T$ ”.