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# Erratum to “Adaptive observers for TS fuzzy systems with unknown polynomial inputs” [Fuzzy Sets and Systems 161 (2010) 2043–2065]\*

Zs. Lendek, J. Lauber, T.M. Guerra, R. Babuška, and B. De Schutter

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Erratum to “Adaptive observers for TS fuzzy systems  
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Zs. Lendek<sup>a,\*</sup>, J. Lauber<sup>b</sup>, T. M. Guerra<sup>b</sup>, R. Babuška<sup>a</sup>, B. De Schutter<sup>a</sup>

<sup>a</sup>*Delft Center for Systems and Control, Delft University of Technology  
Mekelweg 2, 2628 CD Delft, The Netherlands*

<sup>b</sup>*Université de Valenciennes, BP 311, Le Mont Houy, 59313 Valenciennes Cedex 9, France*

**Abstract**

The description of the error dynamics (30) in our paper [1] contains an omission that leads to some bounds used in the conditions of Theorem 8 and Corollary 2 in the paper to be incorrectly defined. In what follows, the correct error dynamics and the corresponding conditions are given.

Instead of (30) in [1], the error dynamics<sup>1</sup> are actually given by

$$\begin{aligned} \dot{\mathbf{e}} &= \sum_{i=1}^m w_i(\mathbf{z})[(A_i - L_i C + M_i A_{\delta i})\mathbf{e} + M_i(\bar{A}_{\delta i}\hat{\mathbf{x}} + \bar{B}_{\delta i}\mathbf{u} + \bar{\theta}_i)] \\ \mathbf{e}_y &= C\mathbf{e} \end{aligned} \quad (1)$$

which leads to  $\mu_{\max}$  in Theorem 8 being given by  $\mu_{\max} \leq \max_i \|M_i A_{\delta i}\|$ , instead of  $\mu_{\max} \leq \max_i \|A_{\delta i}\|$  as stated in [1].

Similarly, the correct error system (36) is given by

$$\begin{aligned} \dot{\mathbf{e}} &= \sum_{i=1}^m w_i(\hat{\mathbf{z}})[(A_i - L_i C + M_i A_{\delta i})\mathbf{e} + M_i(\bar{A}_{\delta i}\hat{\mathbf{x}} + \bar{B}_{\delta i}\mathbf{u} + \bar{\theta}_i)] \\ &+ \sum_{i=1}^m (w_i(\mathbf{z}) - w_i(\hat{\mathbf{z}})) \cdot (A_i \mathbf{x} + B_i \mathbf{u} + M_i(A_{\delta i} \mathbf{x} + B_{\delta i} \mathbf{u} + \theta_i)) \\ \mathbf{e}_y &= C\mathbf{e} \end{aligned} \quad (2)$$

and as a consequence the last condition of Corollary 2 in [1] is

$$\begin{pmatrix} Q - \bar{\mu}I & \sqrt{2}P \\ \sqrt{2}P & I \end{pmatrix} > 0 \quad (3)$$

\*Corresponding author. Tel.:+31 (0)15 27 88573, Fax:+31 (0)15 27 86679

*Email addresses:* z.lendek@tudelft.nl (Zs. Lendek), jimmy.lauber@univ-valenciennes.fr (J. Lauber), thierry.guerra@univ-valenciennes.fr (T. M. Guerra), r.babuska@tudelft.nl (R. Babuška), b.deschutter@tudelft.nl (B. De Schutter)

<sup>1</sup>In [1], the first  $M_i$  in the sum was omitted.

where  $\bar{\mu} = \max_i \|M_i A_{\delta_i}\|^2 + \mu^2$ , i.e., the sum of the squared bounds of the two vanishing disturbances. In [1] only the disturbance arising from the observer-model mismatch was considered.

Note that thanks to the  $M_i$  considered in the example of [1], with  $\|M_i\| = 1$ , the change in the conditions does not affect the numerical results.

## References

- [1] Zs. Lendek, J. Lauber, T. M. Guerra, R. Babuška, B. De Schutter, Adaptive observers for TS fuzzy systems with unknown polynomial inputs, *Fuzzy Sets and Systems* 161 (15) (2010) 2043–2065.