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Erratum to "Adaptive observers for TS fuzzy systems with unknown polynomial inputs" [Fuzzy Sets and Systems 161 (2010) 2043–2065]*

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Erratum to "Adaptive observers for TS fuzzy systems with unknown polynomial inputs" [Fuzzy Sets and Systems 161 (2010) 2043–2065]

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Abstract

The description of the error dynamics (30) in our paper [1] contains an omission that leads to some bounds used in the conditions of Theorem 8 and Corollary 2 in the paper to be incorrectly defined. In what follows, the correct error dynamics and the corresponding conditions are given.

Instead of (30) in [1], the error dynamics¹ are actually given by

$$\dot{\boldsymbol{e}} = \sum_{i=1}^{m} w_i(\boldsymbol{z}) [(A_i - L_i C + M_i A_{\delta i}) \boldsymbol{e} + M_i (\bar{A}_{\delta i} \hat{\boldsymbol{x}} + \bar{B}_{\delta i} \boldsymbol{u} + \bar{\theta}_i)]$$

$$\boldsymbol{e}_y = C \boldsymbol{e}$$
(1)

which leads to μ_{\max} in Theorem 8 being given by $\mu_{\max} \leq \max_i \|M_i A_{\delta i}\|$, instead of $\mu_{\max} \leq \max_i \|A_{\delta i}\|$ as stated in [1].

Similarly, the correct error system (36) is given by

$$\dot{\boldsymbol{e}} = \sum_{i=1}^{m} w_i(\widehat{\boldsymbol{z}})[(A_i - L_i C + M_i A_{\delta i})\boldsymbol{e} + M_i(\bar{A}_{\delta i}\widehat{\boldsymbol{x}} + \bar{B}_{\delta i}\boldsymbol{u} + \bar{\theta}_i)]
+ \sum_{i=1}^{m} (w_i(\boldsymbol{z}) - w_i(\widehat{\boldsymbol{z}})) \cdot (A_i \boldsymbol{x} + B_i \boldsymbol{u} + M_i(A_{\delta i}\boldsymbol{x} + B_{\delta i}\boldsymbol{u} + \theta_i))$$

$$\boldsymbol{e}_y = C\boldsymbol{e} \tag{2}$$

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¹In [1], the first M_i in the sum was omitted.

and as a consequence the last condition of Corollary 2 in [1] is

$$\begin{pmatrix} Q - \bar{\mu}I & \sqrt{2}P\\ \sqrt{2}P & I \end{pmatrix} > 0 \tag{3}$$

where $\bar{\mu} = \max_i \|M_i A_{\delta i}\|^2 + \mu^2$, i.e., the sum of the squared bounds of the two vanishing disturbances. In [1] only the disturbance arising from the observer-model mismatch was considered.

Note that thanks to the M_i considered in the example of [1], with $||M_i|| = 1$, the change in the conditions does not affect the numerical results.

References

[1] Zs. Lendek, J. Lauber, T. M. Guerra, R. Babuška, B. De Schutter, Adaptive observers for TS fuzzy systems with unknown polynomial inputs, Fuzzy Sets and Systems 161 (15) (2010) 2043–2065.