## Delft University of Technology

# Estimation of the generalized traffic average speed based on microscopic measurements: Addendum* 

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# Estimation of the generalized traffic average speed based on microscopic measurements: Addendum 

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#### Abstract

This addendum contains the extended proof of the tight upper and lower bounds (41) and (42) of the manuscript "Estimation of the generalized traffic average speed based on microscopic measurements" by A. Jamshidnejad and B. De Schutter, Oct. 2014.


## A Proof

Suppose that we have the following data from the loop detector:

$$
\begin{gather*}
\mathbf{V}_{A}=\left\{v_{A, i} \mid i=1,2, \ldots, n_{A}\right\}, \\
v_{A, \min }=\min _{i=1, \ldots, n_{A}}\left(v_{A, i}\right),  \tag{A.1}\\
v_{A, \max }=\max _{i=1, \ldots, n_{A}}\left(v_{A, i}\right), \\
h_{A}=\frac{1}{n_{A}} \sum_{i=1}^{n_{A}} h_{A, i-1} \tag{A.2}
\end{gather*}
$$

where this data is according to the sampling window $A$ with length $L_{A}$ and width $T_{A}$. Moreover, the parameters $m_{A}$ and $M_{A}$ could be calculated by (24) and (25). Then from (32) and (35) we obtain the lower and upper bounds for the TSMS, so that we can write:

$$
\begin{equation*}
v^{\text {lower }}(A) \leq \operatorname{TSMS}(A) \leq v^{\operatorname{upper}}(A) \tag{A.3}
\end{equation*}
$$

Now we construct a new sampling window $B$ (see Figure 1) with all speed data the same as that of $A$, but with the headway a different constant, i.e.,

$$
\begin{equation*}
h_{B}=h_{A}+\Delta h \tag{A.4}
\end{equation*}
$$

and

$$
\begin{equation*}
L_{B}=L_{A}, \quad T_{B}=n_{A} h_{B} \tag{A.5}
\end{equation*}
$$

and we want to find $\Delta h$ such that:

$$
\begin{equation*}
v^{\text {lower }}(B) \leq \operatorname{TSMS}(A) \leq v^{\text {upper }}(B) \tag{A.6}
\end{equation*}
$$

Note that $n_{A}=n_{B}$.
From Figure 1 we see that for $\Delta h>0$ some of the vehicles that are located in the second set for $A$, might be located in the first set for $B$. Let $W$ be the number of vehicles from the second set of $A$ that are in the first set for $B$. Then we have:

$$
\begin{equation*}
m_{B}=m_{A}-W \tag{A.7}
\end{equation*}
$$

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Figure 1: Sampling windows $A$ and $B$ with the same data sets (i.e., speed values, number of vehicles, and length of the window), but different time headways (we have $\alpha_{i}>1$ and $\alpha_{i} x_{i}=L_{A}$ )

We start with considering the upper bound of $B$ to find the conditions under which this upper bound is also an upper bound for $\operatorname{TSMS}(A)$. First from (35) for the factor multiplied by $H_{A, 1 \rightarrow n_{A}-m_{A}+1}$, i.e.,

$$
\begin{align*}
& f\left(m_{A}\right)=\frac{n_{A}-\frac{M_{A}}{2}+1}{\left(n_{A}-m_{A}+1\right)+\frac{\left(M_{A}-1\right)}{2 m_{A}}\left(2 m_{A}-M_{A}\right)}  \tag{A.8}\\
& \text { with: } \quad M_{A}=\frac{v_{A, \min }}{v_{A, \max }} m_{A}+1
\end{align*}
$$

we can easily show that $\left(\alpha=\frac{v_{A, \text { min }}}{v_{A, \text { max }}}\right)$ :

$$
\begin{align*}
\frac{\partial f\left(m_{A}\right)}{\partial m_{A}} & =\frac{\left(2 \alpha^{2}-6 \alpha+4\right) n_{A}+2 \alpha^{2}-4 \alpha+2}{4 n_{A}^{2}+\left(f_{1}(\alpha) m_{A}-4 \alpha+8\right) n_{A}+f_{2}(\alpha) m_{A}^{2}+f_{3}(\alpha) m_{A}+\alpha^{2}-4 \alpha+4} \geq 0 \\
f_{1}(\alpha) & =-4 \alpha^{2}+8 \alpha-8  \tag{A.9}\\
f_{2}(\alpha) & =\alpha^{4}-4 \alpha^{3}+8 \alpha^{2}-8 \alpha+4 \\
f_{3}(\alpha) & =2 \alpha-8 \alpha^{2}+12 \alpha-8
\end{align*}
$$

Therefore, by reducing $m_{A}$ to $m_{B}$ (i.e., by increasing $h_{A}$ to $h_{B}$ ), the factor (A.8) becomes smaller and could produce a tighter upper bound (note that the equality occurs for $\alpha=1$, i.e., for uniform speeds).

Now we should find the extreme/worst case where $\operatorname{TSMS}(A)$ might violate $v^{\text {upper }}(B)$. Thus, we will try to strengthen $\operatorname{TSMS}(A)$ and to weaken $v^{\text {upper }}(B)$ at the same time in order to produce the worst possible case. For the given $A$ and $B$, the case where

$$
\begin{equation*}
v_{A, j}=v_{A, \max }, \quad \text { for } \quad j=n_{A}-m_{A}+W, \ldots, n_{A} \tag{A.10}
\end{equation*}
$$

makes $\operatorname{TSMS}(A)$ stronger with respect to $v^{\text {upper }}(B)$, because the speed values of the vehicles in (A.10) would not appear in (35) for $v^{\text {upper }}(B)$, but will strengthen $\operatorname{TSMS}(A)$.

Now we consider the vehicles $v_{A, i}, i=n_{A}-m_{A}, \ldots, n_{A}-m_{A}+W-1$ where these vehicles will appear in both the harmonic mean of the first set of $B$ and in $\operatorname{TSMS}(A)$. We first introduce the following two lemmas:

Lemma 1 For fixed values of $v_{A, j}, j=1,2, \ldots, n_{A}-m_{A}+1$, suppose that we have

$$
\begin{align*}
& \mathrm{H}\left(\left\{v_{A, j} \mid j=1,2, \ldots, n_{A}-m_{A}+1\right\} \cup\left\{v_{A, i} \mid i=n_{A}-m_{A}+2, \ldots, n_{A}-m_{A}+W-1\right\}\right)< \\
& \quad \operatorname{TSMS}\left(\left\{v_{A, j} \mid j=1,2, \ldots, n_{A}-m_{A}+1\right\} \cup\left\{v_{A, i} \mid i=n_{A}-m_{A}+2, \ldots, n_{A}-m_{A}+W-1\right\}\right) \tag{A.11}
\end{align*}
$$

Then, the difference between the two following values

$$
\mathrm{H}\left(\left\{v_{A, j} \mid j=1,2, \ldots, n_{A}-m_{A}+1\right\} \cup\left\{v_{A, i} \mid i=n_{A}-m_{A}+2, \ldots, n_{A}-m_{A}+W-1\right\}\right)
$$

and

$$
\operatorname{TSMS}\left(\left\{v_{A, j} \mid j=1,2, \ldots, n_{A}-m_{A}+1\right\} \cup\left\{v_{A, i} \mid i=n_{A}-m_{A}+2, \ldots, n_{A}-m_{A}+W-1\right\}\right)
$$

becomes maximum, if we have:

$$
\begin{equation*}
v_{A, i}<v_{A, j}, \quad i=n_{A}-m_{A}+2, \ldots, n_{A}-m_{A}+W-1 \tag{A.12}
\end{equation*}
$$

where $\mathrm{H}(\cdot)$ stands for the harmonic mean.
Proof: We denote the traveled distance and the travel time of vehicle $v_{A, k}$ for $k=1, \ldots, n_{A}-m_{A}+1$ by respectively $x_{k}$ and $t_{k}$, and also the traveled distance and the travel time of $v_{A, i}, i=n_{A}-m_{A}+2, \ldots, n_{A}-m_{A}+$ $W-1$ by $x_{i}$ and $t_{i}$. Furthermore, to ease the notations we use " $j \in 1^{\text {st }}$ set of $A$ " to indicate $j=1,2, \ldots, n_{A}-$ $m_{A}+1$. Then we will have:

$$
\begin{align*}
& \operatorname{TSMS}\left(\left\{v_{A, j} \mid j \in 1^{\text {st }} \text { set of } A\right\} \cup v_{A, i}\right)=\frac{x_{1}+\ldots+x_{n_{A}-m_{A}+1}+x_{i}}{t_{1}+\ldots+t_{n_{A}-m_{A}+1}+t_{i}}  \tag{A.13}\\
& \mathrm{H}\left(\left\{v_{A, j} \mid j \in 1^{\text {st }} \text { set of } A\right\} \cup v_{A, i}\right)=\frac{n_{A}-m_{A}+2}{\frac{t_{1}}{x_{1}}+\ldots+\frac{t_{n_{A}-m_{A}+1}}{x_{n_{A}-m_{A}+1}}+\frac{t_{i}}{x_{i}}} \tag{A.14}
\end{align*}
$$

by a few computations and simplifications, we obtain:

$$
\begin{align*}
& \mathrm{H}\left(\left\{v_{A, j} \mid j \in 1^{\text {st }} \text { set of } A\right\} \cup v_{A, i}\right)<\mathrm{TSMS}\left(\left\{v_{A, j} \mid j \in 1^{\text {st }} \text { set of } A\right\} \cup v_{A, i}\right) \\
& \Leftrightarrow \\
& \begin{array}{l}
\left(x_{1}-x_{i}\right) \frac{\left(x_{1} t_{i}-x_{i} t_{1}\right)}{x_{i}} x_{2} \ldots x_{n_{A}-m_{A}+1}+ \\
\vdots \\
+\left(x_{n_{A}-m_{A}+1}-x_{i}\right) \frac{\left(x_{n_{A}-m_{A}+1} t_{i}-x_{i} t_{n_{A}-m_{A}+1}\right)}{x_{i}} x_{1} \ldots x_{n_{A}-m_{A}} \\
+\left(x_{2}-x_{1}\right)\left(x_{2} t_{1}-x_{1} t_{2}\right) x_{3} \ldots x_{n_{A}-m_{A}+1}+ \\
\vdots \\
+\left(x_{n_{A}-m_{A}+1}-x_{n_{A}-m_{A}}\right)\left(x_{n_{A}-m_{A}+1} t_{n_{A}-m_{A}}-x_{n_{A}-m_{A}} t_{n_{A}-m_{A}+1}\right) x_{1} \ldots x_{n_{A}-m_{A}-1}>0
\end{array} \tag{A.15}
\end{align*}
$$

Since the following holds:

$$
x_{1}=\ldots=x_{n_{A}-m_{A}+1}=L_{A} \quad, \quad x_{i} \leq L_{A}
$$

hence,

$$
\begin{equation*}
x_{j}-x_{i} \geq 0 \quad \text { for } \quad j \in 1^{\text {st }} \text { set of } A \tag{A.16}
\end{equation*}
$$

Therefore, if we have:

$$
\begin{equation*}
\frac{x_{j} t_{i}}{x_{i}}-t_{j}>0 \tag{A.17}
\end{equation*}
$$

which is equivalent to:

$$
\begin{equation*}
v_{A, j}>v_{A, i} \tag{A.18}
\end{equation*}
$$

the boxed terms in (A.15) will definitely be positive. From (A.17) to make the boxed terms maximum, we should have:

$$
v_{A, i}=v_{A, \min }
$$

The same reasoning holds when more than one vehicle $v_{A, i}$ is considered, i.e., if we consider

$$
\begin{equation*}
v_{A, i}=v_{A, \min }, \quad \text { for } \quad i=n_{A}-m_{A}+2, \ldots, n_{A}-m_{A}+W-1 \tag{A.19}
\end{equation*}
$$

then (A.11) will be satisfied and the difference between the two terms given by Lemma 1 will be maximum.

Lemma 2 For $N, a \geq 0$ and $D, b>0$ we will have: $\frac{a}{b} \geq \frac{N}{D} \Leftrightarrow \frac{N+a}{D+b} \geq \frac{N}{D}$.
As explained before, we are looking for the extreme case. Hence we suppose to have the conditions given by Lemma 1, which based on Lemma 2 and (A.10) indicate that:

$$
\begin{equation*}
\operatorname{TSMS}(A) \geq \operatorname{TSMS}\left(\left\{v_{A, j} \mid j \in 1^{\text {st }} \text { set of } A\right\} \cup v_{A, i}\right) \tag{A.20}
\end{equation*}
$$ and hence,

$$
\begin{equation*}
\operatorname{TSMS}(A) \geq \mathrm{H}\left(\left\{v_{A, j} \mid j \in 1^{\text {st }} \text { set of } A\right\} \cup v_{A, i}\right) \tag{A.21}
\end{equation*}
$$

Thus the worst case occurs if we have both (A.10) and (A.19).

Now we can write $\operatorname{TSMS}(A)$ and $v^{\text {upper }}(B)$ for the worst case, as follows. First for $\operatorname{TSMS}(A)$ :
$\operatorname{TSMS}(A)=\frac{\sum_{A, x}+v_{A, \min }\left[W \frac{L_{A}}{v_{A, \text { min }}}-\frac{W(W+1)}{2} h_{A}\right]+v_{A, \max }\left[\left(m_{A}-W-1\right) \frac{L_{A}}{v_{A, \text { max }}}-\frac{\left(M_{A}-1\right)\left(M_{A}-2\right)}{2} h_{A}\right]}{\sum_{A, t}+W \frac{L_{A}}{v_{A, \text { min }}}-\frac{W(W+1)}{2} h_{A}+\left(m_{A}-W-1\right) \frac{L_{A}}{v_{A, \max }}-\frac{\left(M_{A}-1\right)\left(M_{A}-2\right)}{2} h_{A}}$
where

$$
\sum_{A, x}=\sum_{j=1}^{n_{A}-m_{A}+1} v_{A, j} t_{A, j} \quad, \quad \sum_{A, t}=\sum_{j=1}^{n_{A}-m_{A}+1} t_{A, j}
$$

are the traveled distance and the travel time of the first set of vehicles in $A$. The second term of the denominator corresponds to the travel time of the first $W$ vehicles located in the second set of $A$, for which we have:

$$
\begin{aligned}
\sum_{j=n_{A}-m_{A}+1}^{n_{A}-m_{A}+W} t_{A, j}=\left(\frac{L_{A}}{v_{A, \min }}-h_{A}\right)+\left(\frac{L_{A}}{v_{A, \min }}-2 h_{A}\right) & +\ldots+\left(\frac{L_{A}}{v_{A, \min }}-W h_{A}\right) \\
= & W \frac{L_{A}}{v_{A, \min }}-\frac{W(W+1)}{2} h_{A}
\end{aligned}
$$

and the second term of the numerator corresponds to the traveled distance of the first $W$ vehicles located in the second set of $A$.

The third term of the denominator corresponds to the travel time of the last $m_{A}-W-1$ vehicles located in the second set of $A$, for which we have:

$$
\begin{gather*}
\sum_{j=n_{A}-m_{A}+W+1}^{n_{A}} t_{A, j}=\left(m_{A}-W-1-\left(M_{A}-2\right)\right) \frac{L_{A}}{v_{A, \max }}+ \\
\left(M_{A}-2\right)\left[\left(\frac{L_{A}}{v_{A, \max }}-h_{A}\right)+\left(\frac{L_{A}}{v_{A, \max }}-2 h_{A}\right)+\ldots+h_{A}\right]  \tag{A.23}\\
=\left(m_{A}-W-1\right) \frac{L_{A}}{v_{A, \max }}-\frac{\left(M_{A}-1\right)\left(M_{A}-2\right)}{2} h_{A}
\end{gather*}
$$

and the third term of the numerator corresponds to the traveled distance of the last $m_{A}-W-1$ vehicles located in the second set of $A$.

Now we consider the upper bound for the sampling window $B$. Here we know that the first $W$ vehicles in the second set of $A$ are located in the first set of $B$. Extension of the headway (or the width of the sampling window) might also have an effect on the number of vehicles in the second subset of $B$ (i.e., the last $M_{B}-2$ vehicles in the second set). Therefore, in general we consider $W^{\prime}$ number of vehicles that were in the second subset of $A$ are now out of this subset for $B$. Consequently we will have:

$$
M_{B}=M_{A}-W^{\prime}
$$

For the upper bound for $B$ from (34) we can write:

$$
\begin{equation*}
v^{\operatorname{upper}}(B)=\frac{\sum_{x}+v_{A, \min } \frac{W L_{A}}{v_{A, \min }}+v_{A, \max }\left[\frac{\left(m_{A}-W-1\right) L_{A}}{v_{A, \max }}-\frac{\left(M_{A}-W^{\prime}-1\right)\left(M_{A}-W^{\prime}-2\right)}{2}\left(h_{A}-\Delta h_{A}\right)\right]}{\sum_{A, t}+\frac{W L_{A}}{v_{A, \text { min }}}+\frac{\left(m_{A}-W-1\right) L_{A}}{v_{A, \max }}-\frac{\left(M_{A}-W^{\prime}-1\right)\left(M_{A}-W^{\prime}-2\right)}{2}\left(h_{A}-\Delta h\right)} \tag{A.24}
\end{equation*}
$$

where the following summations in the numerator and denominator of $v^{\text {upper }}(B)$ represent the traveled distance and the travel time of the first set of the sampling window $B$ respectively:

Traveled distance of the $1^{\text {st }}$ set of $B$ :

$$
\begin{equation*}
\sum_{A, x}+v_{A, \min } \frac{W L_{A}}{v_{A, \min }} \tag{A.25}
\end{equation*}
$$

Travel time of the $1^{\text {st }}$ set of $B$ :

$$
\sum_{A, t}+\frac{W L_{A}}{v_{A, \min }}
$$

Also the following two terms are the traveled distance and the travel time of the second set of the sampling window $B$ :

Traveled distance of the $2^{\text {nd }}$ set of $B$ :

$$
v_{A, \max }\left[\frac{\left(m_{A}-W-1\right) L_{A}}{v_{A, \max }}-\frac{\left(M_{A}-W^{\prime}-1\right)\left(M_{A}-W^{\prime}-2\right)}{2}\left(h_{A}-\Delta h\right)\right]
$$

Travel time of the $2^{\text {nd }}$ set of $B$ :

$$
\frac{\left(m_{A}-W-1\right) L_{A}}{v_{A, \max }}-\frac{\left(M_{A}-W^{\prime}-1\right)\left(M_{A}-W^{\prime}-2\right)}{2}\left(h_{A}-\Delta h\right)
$$

Now we apply Lemma 3 (see Appendix B) to see what conditions are needed for (A.57) to be applicable to (A.22) and (A.24). Equations (A.22) and (A.24) could be rewritten as:

$$
\begin{equation*}
\operatorname{TSMS}(A)=\frac{\operatorname{TSMS}\left(\left\{v_{A, j} \mid j \in 1^{\text {st }} \text { set of } A\right\}\right) \sum_{A, t}+c_{1}^{\prime} \cdot v_{A, \max }+c_{2}^{\prime} \cdot v_{A, \min }}{\sum_{A, t}+c_{1}^{\prime}+c_{2}^{\prime}} \tag{A.26}
\end{equation*}
$$

where

$$
\begin{equation*}
c_{1}^{\prime}=\frac{\left(m_{A}-W-1\right) L_{A}}{v_{A, \max }}-\frac{\left(M_{A}-1\right)\left(M_{A}-2\right)}{2} h_{A} \tag{A.27}
\end{equation*}
$$

and

$$
\begin{equation*}
c_{2}^{\prime}=\frac{W L_{A}}{v_{A, \min }}-\frac{W(W+1)}{2} h_{A} \tag{A.28}
\end{equation*}
$$

normalizing the coefficients with respect to $\sum_{A, t}$,

$$
\begin{equation*}
\operatorname{TSMS}(A)=\frac{\operatorname{TSMS}\left(\left\{v_{A, j} \mid j \in 1^{\text {st }} \text { set of } A\right\}\right)+\frac{c_{1}^{\prime}}{\sum_{A, t}} \cdot v_{A, \max }+\frac{c_{2}^{\prime}}{\sum_{A, t}} \cdot v_{A, \min }}{1+\underbrace{\sum_{A, t}}_{w_{1}^{\prime}}+\underbrace{\sum_{A, t}^{\prime}}_{w_{2}^{\prime}}} \tag{A.29}
\end{equation*}
$$

Similarly,

$$
\begin{equation*}
v^{\operatorname{upper}}(B)=\frac{\operatorname{TSMS}\left(\left\{v_{A, j} \mid j \in 1^{\text {st }} \text { set of } A\right\}\right)+\frac{c_{1}}{\sum_{A, t}} \cdot v_{A, \max }+\frac{c_{2}}{\sum_{A, t}} \cdot v_{A, \min }}{1+\underbrace{\frac{c_{1}}{\sum_{A, t}}}_{w_{1}}+\underbrace{\frac{c_{2}}{\sum_{A, t}}}_{w_{2}}} \tag{A.30}
\end{equation*}
$$

with

$$
\begin{equation*}
c_{1}=\frac{\left(m_{A}-W-1\right) L_{A}}{v_{A, \max }}-\frac{\left(M_{A}-W^{\prime}-1\right)\left(M_{A}-W^{\prime}-2\right)}{2}\left(h_{A}-\Delta h_{A}\right) \tag{A.31}
\end{equation*}
$$

and

$$
\begin{equation*}
c_{2}=\frac{W L_{A}}{v_{A, \min }} \tag{A.32}
\end{equation*}
$$

Therefore, case C2 of the lemma 3 holds for (A.29) and (A.30) if we have:

$$
\frac{\left.\left(m_{A}-W-1\right) \frac{L_{A}}{v_{A, \max }}-\frac{\left(M_{A}-W^{\prime}-1\right)\left(M_{A}-W^{\prime}-2\right)}{2} h_{A}+\left(n_{A}-m_{A}+1\right)\left(M_{A}-1\right) h_{A}\right]^{N^{\prime}}+\frac{\left(M_{A}-W^{\prime}-1\right)\left(M_{A}-W^{\prime}-2\right)}{2} \Delta h}{W^{W} \frac{L_{A}}{v_{A, \min }}-\frac{W(W+1)}{2} h_{A}+\frac{W(W+1)}{2} h_{A}}
$$

$\geq \frac{\left.\left(m_{A}-W-1\right) \frac{L_{A}}{v_{A, \text { max }}}-\frac{\left(M_{A}-1\right)\left(M_{A}-2\right)}{2} h_{A}+\left(n_{A}-m_{A}+1\right)\left(M_{A}-1\right) h_{A}\right]^{N}}{W^{W} \frac{L_{A}}{v_{A, \text { min }}}-\frac{W(W+1)}{2} h_{A}}$
Note that from lemma 3 the extreme case where the inequality given by (A.57) might be violated takes place for $X=X_{\max }$ or equivalently

$$
\operatorname{TSMS}\left(\left\{v_{A, j} \mid j \in 1^{\text {st }} \text { set of } A\right\}\right)=v_{A, \max } \Rightarrow \sum_{A, t}=\left(n_{A}-m_{A}+1\right)\left(M_{A}-1\right) h_{A}
$$

Next we use Lemma 2, where for (A.33),

$$
\begin{gathered}
a=\frac{\left(M_{A}-W^{\prime}-1\right)\left(M-W^{\prime}-2\right)}{2} \Delta h+\frac{W^{\prime}\left(2 M_{A}-W^{\prime}-3\right)}{2} h_{A} \\
b=\frac{W(W+1)}{2} h
\end{gathered}
$$

Since $W^{\prime}<M_{A}-2$, then $W^{\prime}=M_{A}-3$ makes $a$ minimum. Now, if the following holds:

$$
\begin{align*}
& \frac{\left(M_{A}-\left(M_{A}-3\right)-1\right)\left(M_{A}-\left(M_{A}-3\right)-2\right)}{2} \Delta h+\frac{\left(M_{A}-3\right)\left(2 M_{A}-\left(M_{A}-3\right)-3\right)}{2} h_{A}  \tag{A.34}\\
& \frac{\left(m_{A}-W(W+1)\right.}{2} h_{A} \\
& W m_{A} h_{A}-\frac{W(W+1)}{2} h_{A}
\end{align*}
$$

which can be simplified to the following expression:

$$
\begin{equation*}
\Delta h \geq \frac{n_{A} M_{A} W-M_{A} W^{2}-n_{A} W^{2}-n_{A} W-M_{A}^{2} m_{A}-\frac{1}{2} M_{A} W}{2 m_{A}-W-1} h_{A} \tag{A.35}
\end{equation*}
$$

In addition we have:

$$
\begin{equation*}
\left(m_{A}-W\right)\left(h_{A}+\Delta h\right)=m_{A} h_{A} \Rightarrow \Delta h_{A}=\frac{W}{m_{A}-W} h_{A} \tag{A.36}
\end{equation*}
$$

Substituting (A.36) in (A.35) we will finally get:

$$
\begin{equation*}
W \geq \frac{n_{A}\left(M_{A}-1\right)}{n_{A}+M_{A}} \tag{A.37}
\end{equation*}
$$

and if we also have:

$$
\begin{gather*}
\left(m_{A}-W-1\right)\left(M_{A}-1\right) h_{A}-\frac{\left(M_{A}-1\right)\left(M_{A}-2\right)}{2} h_{A}+\left(n_{A}-m_{A}+1\right)\left(M_{A}-1\right) h_{A} \geq 0 \Leftrightarrow \\
W \leq n_{A}-\frac{M_{A}}{2}+1 \tag{A.38}
\end{gather*}
$$

then based on lemma 2 (A.24) will be an upper bound for (A.22).
In addition, we know that in (A.24), the vehicles in the second subset of $B$ compensate for the reduction of $v^{\text {upper }}(B)$ due to the $W$ last vehicles in the first set that move with $v_{A, \min }$. Therefore, we need to make sure that

$$
\begin{equation*}
h_{B} \leq\left(M_{A}-1\right) h_{A} \tag{A.39}
\end{equation*}
$$

Then for the extreme case we will have:

$$
m_{A}-W \geq \frac{m_{A} h_{A}}{\left(M_{A}-1\right) h_{A}} \Rightarrow W \leq m_{A} \frac{\left(M_{A}-2\right)}{M_{A}-1}
$$

and finally we should have:

$$
\begin{equation*}
W \leq \min \left\{m_{A} \frac{M_{A}-2}{M_{A}-1}, n_{A}-\frac{M_{A}}{2}+1\right\} \tag{A.40}
\end{equation*}
$$

Finally, we need to select $W$ such that both (A.37) and (A.40) are satisfied at the same time. Afterwards, from $W$ we can obtain $m_{B}$ using (40), and then from (24) we will have $h_{B}$. Hence, we can obtain $M_{B}$ from (25). Then using $m_{B}$ and $M_{B}$, $\operatorname{TSMS}^{\text {upper }}(B)$ is calculated by (35), while we can make sure that the obtained value is an upper bound for $\operatorname{TSMS}(A)$.

Now, we consider the lower bound of $B$ and we seek for conditions under which this bound is also a lower bound for TSMS $(A)$. With a similar reasoning as we had for the upper bound, here the extreme case where $\operatorname{TSMS}(A)$ might become equal to or less than $v^{\text {lower }}(B)$ is when we have:

$$
\begin{equation*}
v_{A, j}=v_{A, \min }, \quad \text { for } \quad j=n_{A}-m_{A}+W, \ldots, n_{A} \tag{A.41}
\end{equation*}
$$

Additionally, the worst case corresponds to the situation where all the $W$ vehicles (that are located in the second set of $A$, but in the first set of $B$ ) move with $v_{A, \max }$, i.e.,

$$
\begin{equation*}
v_{A, j}=v_{A, \max }, \quad \text { for } \quad j=n_{A}-m_{A}, \ldots, n_{A}-m_{A}+W-1 \tag{A.42}
\end{equation*}
$$

Finally, for $\operatorname{TSMS}(A)$ and $v^{\text {lower }}(B)$ (from (29)) we will have:

$$
\begin{array}{r}
\operatorname{TSMS}(A)=\frac{\sum_{A, x}+v_{A, \max }\left[\frac{W L_{A}}{v_{A, \max }}-\frac{\left(W-m_{A}+M_{A}-1\right)\left(W-m_{A}+M_{A}\right) h_{A}}{2}\right]+v_{A, \min } \frac{\left(m_{A}-W-1\right)\left(m_{A}-W\right) h_{A}}{2}}{\sum_{A, t}+\frac{W L_{A}}{v_{A, \max }}-\frac{\left(W-m_{A}+M_{A}-1\right)\left(W-m_{A}+M_{A}\right) h_{A}}{2}+\frac{\left(m_{A}-W-1\right)\left(m_{A}-W\right) h_{A}}{2}} \\
v^{\operatorname{lower}}(B)=\frac{\sum_{A, x}+v_{A, \max } \frac{W L_{A}}{v_{A, \max }}+v_{A, \min } \frac{\left(m_{A}-W-1\right)\left(m_{A}-W\right)}{2}\left(h_{A}+\Delta h\right)}{\sum_{A, t}+\frac{W L_{A}}{v_{A, \max }}+\frac{\left(m_{A}-W-1\right)\left(m_{A}-W\right)}{2}\left(h_{A}+\Delta h\right)} \tag{A.44}
\end{array}
$$

The second term of the numerator of (A.43) corresponds to the first $W$ vehicles in the second set of $A$. From (A.42) these move with $v_{A, \max }$. Hence, the travel time of the first $W$ vehicles in the $2^{\text {nd }}$ set of $A$ is:

$$
\begin{equation*}
\underbrace{\frac{L_{A}}{v_{A, \max }}\left(m_{A}-M_{A}+1\right)}_{\text {vehicles in set 2, but outside of subset } 2 \text { of } A}+\underbrace{\left[\left(\frac{L_{A}}{v_{A, \max }}-h_{A}\right)+\ldots+\left(\frac{L_{A}}{v_{A, \max }}-\left(W-m_{A}+M_{A}-1\right) h_{A}\right)\right]}_{\text {vehicles in subset } 2 \text { of } A} \tag{A.45}
\end{equation*}
$$

For (A.43) the third term of the numerator is corresponding to the last $m_{A}-W-1$ vehicles in the second set of $A$, i.e., the vehicles given by (A.41). We know that the travel time of $v_{A, n_{A}}$ is $h_{A}$, for $v_{A, n_{A}-1}$ it is $2 h_{A}$, and so on. Therefore:

Travel time of the last $m_{A}-W-1$ vehicles in the $2^{\text {nd }}$ set of $A$ :

$$
\begin{equation*}
h_{A}+2 h_{A}+\ldots+\left(m_{A}-W-1\right) h_{A}=\frac{\left(m_{A}-W-1\right)\left(m_{A}-W\right) h_{A}}{2} \tag{A.46}
\end{equation*}
$$

For (A.44) the second term corresponds to the $W$ vehicles that are in the second set of $A$, but in the first set of $B$. The third term corresponds to the vehicles in the second set of $B$, where:

Travel time of the vehicles in the $2^{\text {nd }}$ set of $B$ :

$$
\begin{equation*}
\left(h_{A}+\Delta h\right)+2\left(h_{A}+\Delta h\right)+\ldots+\left(m_{A}-W-1\right)\left(h_{A}+\Delta h\right) \tag{A.47}
\end{equation*}
$$

At the end, comparing (A.43) and (A.44) with the cases given in Lemma A.1., case C3 is applicable here. Therefore, if we have:

$$
\begin{align*}
& \frac{W L_{A}}{v_{A, \max }}-\frac{\left(W-m_{A}+M_{A}-1\right)\left(W-m_{A}+M_{A}\right)}{2} h_{A} \\
& \frac{\left(m_{A}-W-1\right)\left(m_{A}-W\right)}{2} h_{A}+\left(n_{A}-m_{A}+1\right) m_{A} h_{A}  \tag{A.48}\\
\geq & \frac{\frac{W L_{A}}{v_{A, \max }}-\frac{\left(W-m_{A}+M_{A}-1\right)\left(W-m_{A}+M_{A}\right)}{2} h_{A}+\frac{\left(W-m_{A}+M_{A}-1\right)\left(W-m_{A}+M_{A}\right)}{2} h_{A}}{\frac{\left(m_{A}-W-1\right)\left(m_{A}-W\right)}{2} h_{A}+\left(n_{A}-m_{A}+1\right) m_{A} h_{A}+\frac{\left(m_{A}-W-1\right)\left(m_{A}-W\right)}{2} \Delta h}
\end{align*}
$$

Now we apply Lemma 2 (the contrapositive of the conditional statement). We obtain:

$$
\begin{equation*}
\frac{\frac{W L_{A}}{v_{A, \max }}-\frac{\left(W-m_{A}+M_{A}-1\right)\left(W-m_{A}+M_{A}\right)}{2} h_{A}}{\frac{\left(m_{A}-W-1\right)\left(m_{A}-W\right)}{2} h_{A}+\left(n_{A}-m_{A}+1\right) m_{A} h_{A}} \geq \frac{\frac{\left(W-m_{A}+M_{A}-1\right)\left(W-m_{A}+M_{A}\right)}{2} h_{A}}{\frac{\left(m_{A}-W-1\right)\left(m_{A}-W\right)}{2} \Delta h} \tag{A.49}
\end{equation*}
$$

which reduces to

$$
\begin{equation*}
\Delta h \geq \frac{\left(W-m_{A}+M_{A}-1\right)\left(W-m_{A}+M_{A}\right)\left[\left(W+m_{A}\right)\left(W-m_{A}+1\right)+2 m_{A}\left(n_{A}-W\right)\right]}{\left(m_{A}-W-1\right)\left(m_{A}-W\right)\left[-W^{2}+(2 m-1) W+\left(M^{2}-2 m M+M^{2}-M+m\right)\right]} h_{A} \tag{A.50}
\end{equation*}
$$

and if in addition to (A.50) we have:

$$
\begin{equation*}
2 W\left(M_{A}-1\right)-\left(W-m_{A}+M_{A}-1\right)\left(W-m_{A}+M_{A}\right) \geq 0 \tag{A.51}
\end{equation*}
$$

which reduces to

$$
\begin{equation*}
W \leq m_{A}+\sqrt{\left(2 m_{A}-M_{A}\right)\left(M_{A}-1\right)}-\frac{1}{2} \tag{A.52}
\end{equation*}
$$

then we can make sure that based on case C3 of Lemma 3:

$$
\mathrm{TSMS}^{\text {lower }}(B) \leq \operatorname{TSMS}(A)
$$

Then similar to what we explained for the upper bound before, we will have $m_{B}$ and $M_{B}$ and correspondingly $\operatorname{TSMS}^{\text {lower }}(B)$ from (32), which could be used as a lower bound for $\operatorname{TSMS}(A)$.
Note that a simple choice for $W$ from (A.50) and (A.52) is the following which indeed satisfies both conditions:

$$
\begin{equation*}
W \leq m_{A}-M_{A}+1 \tag{A.53}
\end{equation*}
$$

## B Weighted-average lemma

Lemma 3 If for $w_{1}, w_{1}^{\prime}, w_{2}, w_{2}^{\prime} \geq 0$ we have either of:
C1.

$$
\begin{equation*}
w_{1}>w_{1}^{\prime} \quad \text { and } \quad w_{2}<w_{2}^{\prime} \quad \text { and } \quad \frac{w_{1}}{w_{2}} \geq \frac{w_{1}^{\prime}}{w_{2}^{\prime}} \tag{A.54}
\end{equation*}
$$

C2.

$$
\begin{equation*}
w_{1}>w_{1}^{\prime} \quad \text { and } \quad w_{2}>w_{2}^{\prime} \quad \text { and } \quad \frac{w_{1}+1}{w_{2}} \geq \frac{w_{1}^{\prime}+1}{w_{2}^{\prime}} \tag{A.55}
\end{equation*}
$$

C3.

$$
\begin{equation*}
w_{1}<w_{1}^{\prime} \quad \text { and } \quad w_{2}<w_{2}^{\prime} \quad \text { and } \quad \frac{w_{1}}{w_{2}+1} \geq \frac{w_{1}^{\prime}}{w_{2}^{\prime}+1} \tag{A.56}
\end{equation*}
$$

then we will have

$$
\begin{equation*}
\frac{X+w_{1} X_{\max }+w_{2} X_{\min }}{1+w_{1}+w_{2}} \geq \frac{X+w_{1}^{\prime} X_{\max }+w_{2}^{\prime} X_{\min }}{1+w_{1}^{\prime}+w_{2}^{\prime}} \tag{A.57}
\end{equation*}
$$

Proof : First, we will consider the following definition:

$$
\begin{equation*}
D=\left(X_{\max }-X_{\min }\right) \underbrace{\left(w_{1} w_{2}^{\prime}-w_{1}^{\prime} w_{2}\right)}_{F_{1}}+\left(X_{\max }-X\right) \underbrace{\left(w_{1}-w_{1}^{\prime}\right)}_{F_{2}}+\left(X-X_{\min }\right) \underbrace{\left(w_{2}^{\prime}-w_{2}\right)}_{F_{3}} \tag{A.58}
\end{equation*}
$$

At this step we reduce the problem to the proof of $D \geq 0$. The equivalency of (A.57) and (A.58) being positive is as follows:

$$
\begin{align*}
& D \geq 0 \Leftrightarrow \\
& \left(X_{\max }-X_{\min }\right)\left(w_{1} w_{2}^{\prime}-w_{1}^{\prime} w_{2}\right)+\left(X_{\max }-X\right)\left(w_{1}-w_{1}^{\prime}\right)+\left(X-X_{\min }\right)\left(w_{2}^{\prime}-w_{2}\right) \geq 0 \Leftrightarrow \\
& w_{1} w_{2}^{\prime} X_{\max }-w_{1} w_{2}^{\prime} X_{\min }-w_{1}^{\prime} w_{2} X_{\max }+w_{1}^{\prime} w_{2} X_{\min }+ \\
& \\
& w_{1} X_{\max }-w_{1} X-w_{1}^{\prime} X_{\max }+w_{1}^{\prime} X+  \tag{A.59}\\
& \quad w_{2}^{\prime} X-w_{2}^{\prime} X_{\min }-w_{2} X+w_{2} X_{\min } \geq 0 \Leftrightarrow \\
& w_{1} w_{2}^{\prime} X_{\max }+w_{1}^{\prime} w_{2} X_{\min }+w_{1} X_{\max }+w_{1}^{\prime} X+w_{2}^{\prime} X+w_{2} X_{\min }+X+w_{1}^{\prime} w_{1} X_{\max }+w_{2}^{\prime} w_{2} X_{\min } \\
& \quad \geq w_{1}^{\prime} w_{2} X_{\max }+w_{1} X+w_{1}^{\prime} X_{\max }+w_{2}^{\prime} X_{\min }+w_{2} X+X+w_{1}^{\prime} w_{1} X_{\max }+w_{2}^{\prime} w_{2} X_{\min } \Leftrightarrow \\
& \left(X+w_{1} X_{\max }+w_{2} X_{\min }\right)\left(1+w_{1}^{\prime}+w_{2}^{\prime}\right) \geq\left(X+w_{1}^{\prime} X_{\max }+w_{2}^{\prime} X_{\min }\right)\left(1+w_{1}^{\prime}+w_{2}^{\prime}\right) \\
& \\
& \stackrel{\text { since } w_{1}, w_{1}^{\prime}, w_{2}, w_{2}^{\prime} \geq 0}{\Longleftrightarrow} \frac{X+w_{1} X_{\max }+w_{2} X_{\min }}{1+w_{1}+w_{2}} \geq \frac{X+w_{1}^{\prime} X_{\max }+w_{2}^{\prime} X_{\min }}{1+w_{1}^{\prime}+w_{2}^{\prime}}
\end{align*}
$$

All the terms $X_{\max }-X_{\min }, X_{\max }-X$, and $X-X_{\min }$ in (A.58) are non-negative. Now we study three cases:

1. Suppose that we have (A.54). Hence, we already know that $F_{1}, F_{2}$, and $F_{3}$ in (A.58) are positive. Then we will know definitely that $D$ is non-negative.
2. Suppose that we have (A.55). Considering (A.58) the minimum value of $D$ is obtained when $X=X_{\max }$ and hence the value that is multiplied by the negative factor $F_{3}$ adopts its maximum value. Therefore (A.58) will reduce to:

$$
\begin{equation*}
D_{\mathrm{C} 2}=\left(X_{\max }-X_{\min }\right)\left(w_{1} w_{2}^{\prime}-w_{1}^{\prime} w_{2}+w_{2}^{\prime}-w_{2}\right) \tag{A.60}
\end{equation*}
$$

Then from (A.55) we could write:

$$
\begin{align*}
& \frac{w_{1}+1}{w_{2}} \geq \frac{w_{1}^{\prime}+1}{w_{2}^{\prime}} \Leftrightarrow  \tag{A.61}\\
& \left(w_{1}+1\right) w_{2}^{\prime} \geq\left(w_{1}^{\prime}+1\right) w_{2} \Leftrightarrow w_{1} w_{2}^{\prime}-w_{1}^{\prime} w_{2}+w_{2}^{\prime}-w_{2} \geq 0
\end{align*}
$$

Hence $D_{\mathrm{C} 2}$ will definitely be non-negative and so will $D$.
3. Suppose that we have (A.56). Then the minimum value of $D$ is obtained when $X=X_{\min }$ and the value multiplied by the negative factor $F_{2}$ adopts its maximum value. Therefore (A.58) will reduce to:

$$
\begin{equation*}
D_{\mathrm{C} 3}=\left(X_{\max }-X_{\min }\right)\left(w_{1} w_{2}^{\prime}-w_{1}^{\prime} w_{2}+w_{1}-w_{1}^{\prime}\right) \tag{A.62}
\end{equation*}
$$

Then from (A.56) we could write:

$$
\begin{align*}
& \frac{w_{1}}{w_{2}+1} \geq \frac{w_{1}^{\prime}}{w_{2}^{\prime}+1} \Leftrightarrow  \tag{A.63}\\
& w_{1}\left(w_{2}^{\prime}+1\right) \geq w_{1}^{\prime}\left(w_{2}+1\right) \Leftrightarrow w_{1} w_{2}^{\prime}-w_{1}^{\prime} w_{2}+w_{1}-w_{1}^{\prime} \geq 0
\end{align*}
$$

Then $D_{\mathrm{C} 3}$ will definitely be non-negative.


[^0]:    *This report can also be downloaded via https://pub.deschutter.info/abs/14_013.html

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