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On the boolean minimal realization problem in the max-plus algebra: Addendum

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In this addendum we present an upper bound for the minimal system order of a max-linear time-invariant DES that can be computed very efficiently, and we give some lemmas that characterize the *ultimate* behavior of the sequence $\{A^{\otimes k}\}_{k=0}^{\infty}$ for a matrix $A \in \mathbb{R}_{\varepsilon}^{n \times n}$.

A Upper bounds for the minimal system order

Definition A.1 (Ultimately geometric impulse response [12, A4])

Let $\{G_k\}_{k=0}^{\infty}$ be the impulse response of a max-linear time-invariant DES. If

$$\exists k_0 \in \mathbb{N}, \ \exists c \in \mathbb{N}_0, \ \exists \lambda \in \mathbb{R}_{\varepsilon} \ such \ that \ \forall k \ge k_0 \ : \ G_{k+c} = \lambda^{\otimes^{\circ}} \otimes G_k \ , \tag{A.1}$$

then we say that the impulse response $\{G_k\}_{k=0}^{\infty}$ is ultimately geometric.

Note that an ultimately geometric sequence $G = \{G_k\}_{k=0}^{\infty}$ is also ultimately periodic. Furthermore, the smallest integers c and k_0 for which (A.1) holds, correspond to respectively the period of G and the length of the transient part of G.

Suppose that we have a DES that can be characterized by a triple (A, B, C). A sufficient but not necessary condition for the impulse response of this DES to be ultimately geometric is that A is irreducible (cf. Theorem 2.4). This will, e.g., be the case for a DES without separate independent subsystems, and with a cyclic behavior or with feedback from the output to the input (such as, e.g., a flexible production system in which the parts are carried around on a limited number of pallets that circulate in the system [3]).

Definition A.2 (Max-plus-algebraic weak column rank [11, 12]) Let $A \in \mathbb{R}^{m \times n}_{\varepsilon}$. If $A \neq \mathcal{E}_{m \times n}$ then the max-plus-algebraic weak column rank of A is defined by

$$\operatorname{rank}_{\oplus,\mathrm{wc}}(A) = \min\left\{ \#I \mid I \subseteq \{1, 2, \dots, n\} \text{ and } \forall k \in \{1, 2, \dots, n\}, \\ \exists l \in \mathbb{N}_0, \exists i_1, i_2, \dots, i_l \in I, \exists \alpha_1, \alpha_2, \dots, \alpha_l \in \mathbb{R}_{\varepsilon} \\ \text{such that } A_{.,k} = \bigoplus_{j=1}^l \alpha_j A_{.,i_j} \right\}.$$

By definition we have $\operatorname{rank}_{\oplus, \operatorname{wc}}(\mathcal{E}) = 0$.

Efficient methods to compute the max-plus-algebraic weak column rank of a matrix are described in [4, 11, A2]. It is easy to verify that for any matrix $A \in \mathbb{R}^{m \times n}_{\varepsilon}$ we have $\operatorname{rank}_{\oplus,\operatorname{Schein}}(A) \leq \operatorname{rank}_{\oplus,\operatorname{wc}}(A)$.

Lemma A.3 Let G be an ultimately geometric sequence with period c. Let k_0 be the length of the transient part of G. Then we have

$$\operatorname{rank}_{\oplus,\operatorname{wc}} H(G) = \operatorname{rank}_{\oplus,\operatorname{wc}} \left(H(G) \right)_{\{1,2,\dots,k\},\{1,2,\dots,k\}} \qquad \text{for all } k \ge k_0 + c \quad . \tag{A.2}$$

Proof: We shall prove this lemma for a sequence of numbers $g = \{g_k\}_{k=0}^{\infty}$. The extension of this proof to a sequence of matrices is straightforward.

Define $H_1 = (H(g))_{,\{1,2,\ldots,k_0+c\}}$ and $H_2 = (H(g))_{\{1,2,\ldots,k_0+c\},\{1,2,\ldots,k_0+c\}}$. First we show that $\operatorname{rank}_{\oplus,\mathrm{wc}} H(g) = \operatorname{rank}_{\oplus,\mathrm{wc}} H_1$. Let $k \in \mathbb{N}$. We have

$$(H(G))_{.,k_0+k+1} = \begin{vmatrix} g_{k_0+k} \\ g_{k_0+k+1} \\ g_{k_0+k+2} \\ \vdots \end{vmatrix}$$

Since g is ultimately geometric, there exists a number $\lambda \in \mathbb{R}_{\varepsilon}$ such that $g_{k_0+c+k} = \lambda^{\otimes^c} \otimes g_{k_0+k}$ for all $k \in \mathbb{N}$. Hence, $g_{k_0+rc+k} = \lambda^{\otimes^{rc}} \otimes g_{k_0+k}$ for all $r \in \mathbb{N}_0$ and $k \in \mathbb{N}$, and thus also

$$(H(G))_{,k_0+rc+k+1} = \lambda^{\otimes^{rc}} \otimes (H(G))_{,k_0+k+1}$$
 for all $r \in \mathbb{N}_0$ and $k \in \mathbb{N}$.

This implies that any column $(H(G))_{.,k_0+c+l}$ with $l \in \mathbb{N}_0$ can be written as $\alpha \otimes (H(G))_{.,k_0+s}$ for some $s \in \{1, 2, ..., c\}$ and some $\alpha \in \mathbb{R}_{\varepsilon}$. As a consequence, we have

$$\operatorname{rank}_{\oplus,\mathrm{wc}} H(G) = \operatorname{rank}_{\oplus,\mathrm{wc}} \left(H(G) \right)_{,\{1,2,\dots,k_0+c\}} = \operatorname{rank}_{\oplus,\mathrm{wc}} H_1$$

Using a similar reasoning as the one that has been used above, it can be shown that any row $(H_1)_{k_0+c+l,.}$ with $l \in \mathbb{N}_0$ can be written as $\alpha \otimes (H_1)_{k_0+s,.}$ for some $s \in \{1, 2, ..., c\}$ and some $\alpha \in \mathbb{R}_{\varepsilon}$. So if we have

$$(H_2)_{.,k} = \bigoplus_{j=1}^l \alpha_j (H_2)_{.,i}$$

for some $l, k, i_1, i_2, \ldots, i_l \in \{1, 2, \ldots, k_0 + c\}$ and $\alpha_1, \alpha_2, \ldots, \alpha_l \in \mathbb{R}_{\varepsilon}$, then we also have

$$(H_1)_{,k} = \bigoplus_{j=1}^{l} \alpha_j (H_1)_{,i_j}$$

This implies that $\operatorname{rank}_{\oplus} H_1 = \operatorname{rank}_{\oplus,\mathrm{wc}} (H_1)_{\{1,2,\ldots,k_0+c\},\ldots} = \operatorname{rank}_{\oplus,\mathrm{wc}} H_2.$ Hence, $\operatorname{rank}_{\oplus,\mathrm{wc}} H(G) = \operatorname{rank}_{\oplus,\mathrm{wc}} H_2.$ As a consequence, (A.2) holds.

Remark A.4 Note that Lemma A.3 implies that if G is an ultimately geometric sequence then $\operatorname{rank}_{\oplus,\mathrm{wc}} H(G)$ is finite and can be determined using a finite number of elementary operations.

The max-plus-algebraic sum of sequences is defined as follows. If $G = \{G_k\}_{k=0}^{\infty}$ and $H = \{H_k\}_{k=0}^{\infty}$ with $G_k, H_k \in \mathbb{R}_{\varepsilon}^{l \times m}$ for all $k \in \mathbb{N}$, then $G \oplus H$ is a sequence with $(G \oplus H)_k = G_k \oplus H_k$ for all $k \in \mathbb{N}$.

From Theorem 3.1 it follows that the impulse response of a max-linear time-invariant DES can always be considered as the max-plus-algebraic sum of a finite number of ultimately geometric impulse responses (see also [1, 11, 12]).

Theorem A.5 Let g be the impulse response of a max-linear time-invariant SISO DES with $g \neq \{\varepsilon\}_{k=0}^{\infty}$. Let g_1, g_2, \ldots, g_s be ultimately geometric sequences such that $g = g_1 \oplus g_2 \oplus \cdots \oplus g_s$.

Then there exists a state space realization of g of order $\sum_{i=1}^{s} \operatorname{rank}_{\oplus, \mathrm{wc}} (H(g_i))$.

Proof: See [11, 12].

Proposition A.6 For any ultimately periodic sequence G we can compute a finite upper bound for the minimal system order of the max-linear time-invariant DES the impulse response of which coincides with G using a finite number of elementary operations.

Proof: This is a direct consequence of Lemma A.3 and Theorem A.5. \Box

B The ultimate behavior of the sequence of consecutive maxplus-algebraic matrix powers

If we permute the rows or the columns of the max-plus-algebraic identity matrix, we obtain a max-plus-algebraic permutation matrix. If $P \in \mathbb{R}_{\varepsilon}^{n \times n}$ is a max-plus-algebraic permutation matrix, then we have $P \otimes P^T = P^T \otimes P = E_n$. A matrix $R \in \mathbb{R}_{\varepsilon}^{m \times n}$ is a max-plus-algebraic upper triangular matrix if $r_{ij} = \varepsilon$ for all i, j with i > j.

Lemma B.1 If $A \in \mathbb{R}^{n \times n}_{\varepsilon}$ then there exists a max-plus-algebraic permutation matrix $P \in \mathbb{R}^{n \times n}_{\varepsilon}$ such that the matrix $\hat{A} = P \otimes A \otimes P^{T}$ is a max-plus-algebraic block upper triangular matrix of the form

$$\hat{A} = \begin{bmatrix} \hat{A}_{11} & \hat{A}_{12} & \dots & \hat{A}_{1l} \\ \mathcal{E} & \hat{A}_{22} & \dots & \hat{A}_{2l} \\ \vdots & \vdots & \ddots & \vdots \\ \mathcal{E} & \mathcal{E} & \dots & \hat{A}_{ll} \end{bmatrix}$$
(A.3)

with $l \ge 1$ and where the matrices \hat{A}_{11} , \hat{A}_{22} , ..., \hat{A}_{ll} are square and irreducible. The matrices \hat{A}_{11} , \hat{A}_{22} , ..., \hat{A}_{ll} are uniquely determined to within simultaneous permutation of their rows and columns, but their ordering in (A.3) is not necessarily unique.

Proof: See, e.g., [1]. This lemma is also the max-plus-algebraic equivalent of a result of [A5]. A proof of the uniqueness assertion can be found in [A1] (Theorem $3.2.4^1$).

The form in (A.3) is called the max-plus-algebraic Frobenius normal form of the matrix A. Note that if A is irreducible then there is only one block in (A.3) and then A is a max-plusalgebraic Frobenius normal form of itself.

Let $A \in \mathbb{B}^{n \times n}$ (or $A \in \mathbb{R}^{n \times n}_{\varepsilon}$). If $\hat{A} = P \otimes A \otimes P^T$ is the max-plus-algebraic Frobenius normal form of A, then we have $A = P^T \otimes \hat{A} \otimes P$. Hence,

$$A^{\otimes^k} = \left(P^T \otimes \hat{A} \otimes P\right)^{\otimes^k} = P^T \otimes \hat{A}^{\otimes^k} \otimes P$$

for all $k \in \mathbb{N}$. Therefore, we may consider without loss of generality the sequence $\{\hat{A}^{\otimes k}\}_{k=0}^{\infty}$ instead of the sequence $\{A^{\otimes k}\}_{k=0}^{\infty}$. Furthermore, since the transformation from A to \hat{A} corresponds to a simultaneous reordering of the rows and columns of A (or to a reordering of the vertices of $\mathcal{G}(A)$), we have $c(A) = c(\hat{A})$.

The following lemma is an extension of Theorem 2.4 and a corrected version of a lemma that can be found in [A6]:

¹Although this theorem is stated for (0, 1)-matrices, there is a one-to-one correspondence between a maxplus-algebraic boolean matrix and a (0, 1)-matrix if we let 0 and ε correspond with 1 and 0 respectively.

Lemma B.2 Let $\hat{A} \in \mathbb{R}_{\varepsilon}^{n \times n}$ be a matrix of the form (A.3) where the matrices $\hat{A}_{11}, \ldots, \hat{A}_{ll}$ are square and irreducible. Let λ_i and c_i be respectively the max-plus-algebraic eigenvalue and the cyclicity of \hat{A}_{ii} for $i = 1, \ldots, l$. Define sets $\alpha_1, \ldots, \alpha_l$ such that $\hat{A}_{\alpha_i \alpha_j} = \hat{A}_{ij}$ for all i, j with $i \leq j$. Define

$$\begin{split} S_{ij} &= \left\{ \left\{ i_0, \dots, i_s \right\} \subseteq \left\{ 1, \dots, l \right\} \ \middle| \ i = i_0 < i_1 < \dots < i_s = j \ \text{and} \\ & \hat{A}_{i_r i_{r+1}} \neq \mathcal{E} \ \text{ for } r = 0, \dots, s - 1 \right\} \\ \Gamma_{ij} &= \bigcup_{\gamma \in S_{ij}} \gamma \\ \Lambda_{ij} &= \begin{cases} \left\{ \lambda_t | t \in \Gamma_{ij} \right\} & \text{if } \Gamma_{ij} \neq \emptyset, \\ \left\{ \varepsilon \right\} & \text{if } \Gamma_{ij} = \emptyset, \end{cases} \\ c_{ij} &= \begin{cases} \lim_{\tau \in I} \left\{ c_t \mid t \in \Gamma_{ij} \right\} & \text{if } \Gamma_{ij} \neq \emptyset \text{ and } c_t \neq 0 \text{ for some } t \in \Gamma_{ij}, \\ 1 & \text{otherwise}, \end{cases} \end{split}$$

for all i, j with i < j. We have

$$\forall i, j \in \{1, \dots, l\} \text{ with } i > j : \left(\hat{A}^{\otimes^k}\right)_{\alpha_i \alpha_j} = \mathcal{E}_{n_i \times n_j} \text{ for all } k \in \mathbb{N}.$$
 (A.4)

Moreover, there exists an integer $K \in \mathbb{N}$ such that

$$\forall i \in \{1, \dots, l\}: \left(\hat{A}^{\otimes^{k+c_i}}\right)_{\alpha_i \alpha_i} = \lambda_i^{\otimes^{c_i}} \otimes \left(\hat{A}^{\otimes^k}\right)_{\alpha_i \alpha_i} \quad \text{for all } k \ge K$$
(A.5)

and

$$\forall i, j \in \{1, \dots, l\} \text{ with } i < j, \forall p \in \alpha_i, \forall q \in \alpha_j, \exists \gamma_0, \dots, \gamma_{c_{ij}-1} \in \Lambda_{ij} \text{ such that}$$

$$\left(\hat{A}^{\otimes^{kc_{ij}+c_{ij}+s}}\right)_{pq} = \gamma_s^{\otimes^{c_{ij}}} \otimes \left(\hat{A}^{\otimes^{kc_{ij}+s}}\right)_{pq} \text{ for all } k \ge K \text{ and for } s = 0, \dots, c_{ij} - 1.$$

$$(A.6)$$

Furthermore, for each combination i, j, p, q with $i < j, p \in \alpha_i$ and $q \in \alpha_j$, there exists at least one index $s \in \{0, \ldots, c_{ij} - 1\}$ such that the smallest γ_s for which (A.6) holds is equal to $\max \Lambda_{ij}$.

Proof: See [A3].

If $G = \{G_k\}_{k=0}^{\infty}$ is the impulse response of a max-linear time-invariant DES and if the triple (A, B, C) is a state space realization of the DES, then it follows from Lemmas B.1 and B.2 that the period of G is a divisor of the cyclicity c(A) of the system matrix A.

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